







Evaluation Kit Available

Design Resources

Click here to ask an associate for production status of specific part numbers.

## **MAX32660**

## **General Description**

In the DARWIN family, the MAX32660 is an ultra-low-power, cost-effective, highly-integrated 32-bit microcontroller designed for battery-powered devices and wireless sensors. It combines a flexible and versatile power management unit with the powerful Arm® Cortex®-M4 processor with floating point unit (FPU) in the industry's smallest form factor: 1.6mm x 1.6mm, 16-bump WLP or 4mm x 4mm, 20-pin TQFN-EP, or 3mm x 3mm, 24-pin TQFN-EP.

The MAX32660 enables designs with complex sensor processing without compromising battery life. It also offers legacy designs an easy and cost optimal upgrade path from 8- or 16-bit microcontrollers.

The device supports SPI, UART, and I<sup>2</sup>C communication while also integrating up to 256KB of flash memory and 96KB of RAM to accommodate application and sensor code. An optional bootloader through I<sup>2</sup>C, UART, or SPI is available.

## **Applications**

- Sports Watches
- Fitness Monitors
- Wearable Medical Patches
- Portable Medical Devices
- Industrial Sensors
- IoT
- Optical Modules: QSFP-DD, QSFP, 400G

## **Benefits and Features**

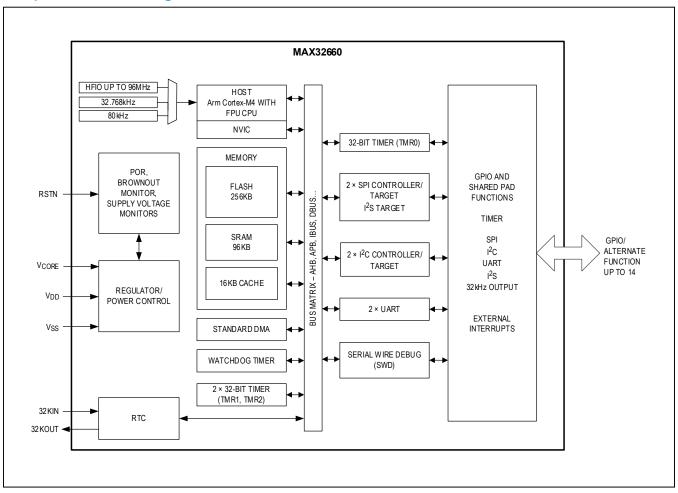
- High-Efficiency Microcontroller for Wearable Devices
  - · Internal Oscillator Operates up to 96MHz
  - 256KB Flash Memory
  - 96KB SRAM, Optionally Preserved in Lowest Power Backup Mode
  - · 16KB Instruction Cache
  - Memory Protection Unit (MPU)
  - Low 1.1V V<sub>CORE</sub> Supply Voltage
  - · 3.6V GPIO Operating Range
  - · Internal LDO Provides Operation from Single Supply
  - Wide Operating Temperature: -40°C to +105°C
- Power Management Maximizes Uptime for Battery Applications
  - 85µA/MHz Active Executing from Flash
  - 2μA Full Memory Retention Power in Backup Mode at V<sub>DD</sub> = 1.8V
  - 450nA Ultra-Low Power RTC at V<sub>DD</sub> = 1.8V
  - · Internal 80kHz Ring Oscillator
- Optimal Peripheral Mix Provides Platform Scalability
  - Up to 14 General-Purpose I/O Pins
  - Up to Two SPI
  - 12S
  - · Up to Two UARTs
  - Up to Two I<sup>2</sup>C, 3.4Mbps High Speed
  - Four-Channel Standard DMA Controller
  - · Three 32-Bit Timers
  - Watchdog Timer
  - CMOS-Level 32.768kHz RTC Output

Ordering Information appears at end of data sheet.

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Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

# **Simplified Block Diagram**



# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

## **Absolute Maximum Ratings**

•	
(All voltages with respect to V <sub>SS</sub> , unless of	therwise noted.)
V <sub>CORE</sub>	0.3V to +1.21V
V <sub>DD</sub>	0.3V to +3.63V
32KIN, 32KOUT	$-0.3V$ to $V_{DD} + 0.3V$
RSTN, All GPIO except P0.[4-7, 9]	$0.3V$ to $V_{DD} + 0.3V$
GPIO P0.[4-7, 9]	$0.3V$ to $V_{DD} + 0.3V$
Total Current into All GPIO Combined (sink	c)100mA
V <sub>SS</sub>	100mA
Output Current (sink) by Any GPIO Pin	25mA
Output Current (source) by Any GPIO Pin.	25mA

Continuous Package Power Dissipation 20 TQFN-EP (multilayer board) TA = +70°C	
(derate 30.3mW/°C above +70°C)	2424.2mW
Continuous Package Power Dissipation	
24 TQFN-EP (multilayer board) T <sub>A</sub> = +70°C	
(derate 16.3mW/°C above +70°C)	1305mW
Operating Temperature Range	-40°C to +105°C
Storage Temperature Range	-65°C to +150°C
Soldering Temperature (reflow)	+260°C

**Note:** Long-term storage at +150°C is not recommended as this will reduce the lifetime of the flash storage. Please keep long-term storage of the part below +125°C.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **Package Information**

#### **16 WLP**

Package Code	W161K1+1
Outline Number	<u>21-100241</u>
Land Pattern Number	Refer to Application Note 1891
Thermal Resistance, Four-Layer Board:	
Junction to Ambient (θ <sub>JA</sub> )	66.34 °C/W
Junction to Case (θ <sub>JC</sub> )	N/A

#### 20 TQFN-EP

Package Code	T2044+5C			
Outline Number	21-0139			
Land Pattern Number	90-0429			
Thermal Resistance, Single-Layer Board:				
Junction to Ambient (θ <sub>JA</sub> )	48°C/W			
Junction to Case $(\theta_{JC})$	2°C/W			
Thermal Resistance, Four-Layer Board:				
Junction to Ambient (θ <sub>JA</sub> )	33°C/W			
Junction to Case (θ <sub>JC</sub> )	2°C/W			

#### 24 TQFN-EP

Package Code	T2433+2C
Outline Number	21-100264
Land Pattern Number	90-100089
Thermal Resistance, Four-Layer Board:	
Junction to Ambient (θ <sub>JA</sub> )	61.3°C/W
Junction to Case (θ <sub>JC</sub> )	2.2°C/W

For the latest package outline information and land patterns (footprints), go to <a href="www.maximintegrated.com/packages">www.maximintegrated.com/packages</a>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to <a href="https://www.maximintegrated.com/thermal-tutorial">www.maximintegrated.com/thermal-tutorial</a>.

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

#### **Electrical Characteristics**

(Limits are 100% tested at  $T_A$  = +25°C and  $T_A$  = +105°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	С	ONDITIONS	MIN	TYP	MAX	UNITS	
POWER SUPPLIES/BOTH	SINGLE SUPP	LY OPERATION A	ND DUAL SUPPLY OPERAT	TION				
Supply Voltage	$V_{DD}$			1.71	1.8	3.63	V	
			OVR = [00]	0.855	0.9	0.945		
Owner by Malkana Com		Dual-supply operation	OVR = [01]	0.95	1.0	1.05	V	
Supply Voltage, Core	$V_{CORE}$	operation	Default OVR = [10]	1.045	1.1	1.155	1	
		Single-supply ope	eration		Not used			
		Monitors V <sub>DD</sub>		1.63		1.71		
Power-Fail Reset Voltage	V <sub>RST</sub>	Monitors V <sub>CORE</sub>	during dual-supply opera-	0.80		0.845	V	
		Monitors V <sub>DD</sub>			1.4			
Power-On Reset Voltage	$V_{POR}$	Monitors V <sub>CORE</sub>	during dual supply opera-		0.65		V	
Sleep Mode Resume Time	t <sub>SLP_ON</sub>				0.57		μs	
Deep Sleep Mode Resume Time	t <sub>DSL_ON</sub>				150		μs	
Backup Mode Resume Time	t <sub>BKU_ON</sub>				150		μs	
POWER SUPPLIES/SINGLE	SUPPLY OP	ERATION (V <sub>DD</sub> O	NLY)					
	$I_{DD\_DACT} \begin{tabular}{ll} total current ir \\ V_{DD} pin, CPU \\ in Active mode \\ inputs tied to \\ V_{SS} \ or \ V_{DD}, \\ \end{tabular}$		HFIO enabled, total current into	OVR = [10], Internal regulator set to 1.1V, f <sub>SYS_CLK(MAX)</sub> = 96MHz		85		
V <sub>DD</sub> Dynamic Current, Active Mode		in Active mode, inputs tied to	OVR = [01], Internal regulator set to 1.0V, fSYS_CLK(MAX) = 48MHz		74		μΑ/MHz	
		outputs source/	OVR = [00], Internal regulator set to 0.9V, fSYS_CLK(MAX) = 24MHz		50			
		HFIO enabled, total current into V <sub>DD</sub> pin, CPU	OVR = [10], Internal regulator set to 1.1V, fSYS_CLK(MAX) = 96MHz		488			
V <sub>DD</sub> Fixed Current, Active Mode	I <sub>DD_FACT</sub>	in Active mode	OVR = [01], Internal regulator set to 1.0V, fSYS_CLK(MAX) = 48MHz		394		μΑ	
	to V <sub>SS</sub> or	to V <sub>SS</sub> or V <sub>DD</sub> , outputs source/ sink 0mA	OVR = [00], Internal regulator set to 0.9V, fSYS_CLK(MAX) = 24MHz		324			

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

## **Electrical Characteristics (continued)**

(Limits are 100% tested at  $T_A$  = +25°C and  $T_A$  = +105°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	С	ONDITIONS	MIN	TYP	MAX	UNITS
		HFIO enabled, total current into	OVR = [10], Internal regulator set to 1.1V, fSYS_CLK(MAX) = 96MHz		30.3		
V <sub>DD</sub> Dynamic Current, Sleep Mode	I <sub>DD_DSLP</sub>	V <sub>DD</sub> pin, CPU in Sleep mode, standard DMA	OVR = [01], Internal regulator set to 1.0V, fsys_CLK(MAX) = 48MHz		27		μΑ/MHz
		with two chan- nels active	OVR = [00], Internal regulator set to 0.9V, fsys_clk(MAX) = 24MHz		24		
		HFIO enabled, total current into V <sub>DD</sub> pin, CPU	OVR = [10], Internal regulator set to 1.1V, fsys_clk(MAX) = 96MHz		485		
V <sub>DD</sub> Fixed Current, Sleep Mode	'DD_FSLP	in Sleep mode, inputs tied to V <sub>SS</sub> or V <sub>DD</sub> ,	OVR = [01], Internal regulator set to 1.0V, fsys_clk(MAX) = 48MHz		391		μA
		outputs source/ sink 0mA	OVR = [00], Internal regulator set to 0.9V, fsys_CLK(MAX) = 24MHz		321		
V <sub>DD</sub> Fixed Current, Deep Sleep Mode	I <sub>DD_FDSL</sub>	Standby state with full data retention and 96kB SRAM retained			4.2		μA
		0KB SRAM retain V <sub>DD</sub> =1.8V	ned with RTC enabled;		0.53		
		16KB SRAM reta V <sub>DD</sub> =1.8V	ined with RTC enabled;		0.99		
V <sub>DD</sub> Fixed Current, Backup Mode	I <sub>DD_FBKU</sub>	32KB SRAM reta V <sub>DD</sub> =1.8V	ined with RTC enabled;		1.20		μA
		64KB SRAM retained with RTC enabled; V <sub>DD</sub> =1.8V 96KB SRAM retained with RTC enabled; V <sub>DD</sub> =1.8V			1.64		
					1.94		
POWER SUPPLIES / DUAL	SUPPLY OPE	RATION (V <sub>DD</sub> AN	D V <sub>CORE</sub> )				•
V <sub>CORE</sub> Dynamic Current, Active Mode	ICORE_DACT	Total current into abled, f <sub>SYS_CLK</sub> ([10], executing cocPU in Active modulo V <sub>DD</sub> ,outputs source.		85		μΑ/MHz	
V <sub>CORE</sub> Fixed Current, Active Mode	I <sub>CORE_FACT</sub>	into V <sub>CORE</sub> pin, (	VR = [10], total current CPU in Active mode 0MHz tied to V <sub>SS</sub> or V <sub>DD</sub> , outputs		403		μA

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

## **Electrical Characteristics (continued)**

(Limits are 100% tested at  $T_A$  = +25°C and  $T_A$  = +105°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
V <sub>DD</sub> Dynamic Current, Active Mode	I <sub>DD_DACT</sub>	HFIO enabled, OVR = [10], $f_{SYS\_CLK(MAX)}$ = 96MHz, total current into $V_{DD}$ pin, executing code from cache memory, CPU in Active mode, inputs tied to $V_{SS}$ or $V_{DD}$ , outputs source/sink 0mA		0.40		μΑ/MHz
V <sub>DD</sub> Fixed Current, Active Mode	I <sub>DD_FACT</sub>	HFIO enabled, OVR = [10], total current into $V_{DD}$ pin, CPU in Active mode 0MHz execution, inputs tied to $V_{SS}$ or $V_{DD}$ , outputs source/sink 0mA		84.8		μА
V <sub>CORE</sub> Dynamic Current, Sleep Mode	I <sub>CORE_DSLP</sub>	HFIO enabled, OVR = [10], total current into $V_{CORE}$ pin, CPU in Sleep mode, standard DMA with two channels active		27.7		µA/MHz
V <sub>CORE</sub> Fixed Current, Sleep Mode	I <sub>CORE_FSLP</sub>	HFIO enabled, OVR [10], total current into V <sub>CORE</sub> pin, CPU in Sleep mode, standard DMA with two channels active		270.3		μА
V <sub>DD</sub> Dynamic Current, Sleep Mode	I <sub>DD_DSLP</sub>	HFIO enabled, OVR = [10], total current into $V_{DD}$ pin, CPU in Sleep mode, standard DMA with two channels active		0.20		µA/MHz
V <sub>DD</sub> Fixed Current, Sleep Mode	I <sub>DD_FSLP</sub>	HFIO enabled, OVR = [10], total current into $V_{DD}$ pin, CPU in Sleep mode, standard DMA with two channels active		65		μА
V <sub>CORE</sub> Fixed Current, Deep-Sleep Mode	I <sub>CORE_FDSL</sub>	V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> =1.1V		5.7		μA
V <sub>DD</sub> Fixed Current, Deep Sleep Mode	IDD_FDSL	V <sub>DD</sub> = 1.8V, V <sub>CORE</sub> =1.1V		4.2		μA
V <sub>CORE</sub> Fixed Current, Backup Mode	I <sub>CORE_FBKU</sub>	V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> = 1.1V, 96KB SRAM retained		5		μA
		0KB SRAM retained with RTC enabled; V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> = 0V or unbiased		0.53		
		16KB SRAM retained with RTC enabled; V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> = 0V or unbiased		0.99		
V <sub>DD</sub> Fixed Current, Backup Mode	I <sub>DD_FBKU</sub>	32KB SRAM retained with RTC enabled; V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> = 0V or unbiased		1.20		μΑ
		64KB SRAM retained with RTC enabled; V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> = 0V or unbiased		1.64		
		96KB SRAM retained with RTC enabled; V <sub>DD</sub> = 1.8V; V <sub>CORE</sub> = 0V or unbiased		1.94		

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

## **Electrical Characteristics (continued)**

(Limits are 100% tested at  $T_A$  = +25°C and  $T_A$  = +105°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
GENERAL-PURPOSE I/O			•				
Input Low Voltage for All GPIO, RSTN	V <sub>IL_GPIO</sub>	Pin configured as GPIO			0.3 × VDD	V	
Input High Voltage for All GPIO, RSTN	V <sub>IH_GPIO</sub>	Pin configured as GPIO	0.7 × V <sub>DD</sub>			V	
		V <sub>DD</sub> = 1.71V, I <sub>OL</sub> = 1mA, DS[1:0] = 00 (Note 1)		0.2	0.4		
Output Low Voltage for All	V	V <sub>DD</sub> = 1.71V, I <sub>OL</sub> = 2mA, DS[1:0] = 10 (Note 1)		0.2	0.4		
GPIO Except P0.2, P0.3, P0.8, and P0.9	V <sub>OL_GPIO</sub>	V <sub>DD</sub> = 1.71V, I <sub>OL</sub> = 4mA, DS[1:0] = 01 (Note 1)		0.2	0.4	V	
		V <sub>DD</sub> = 1.71V, I <sub>OL</sub> = 6mA, DS[1:0] = 11 (Note 1)		0.2	0.4		
Output Low Voltage for		V <sub>DD</sub> = 1.71V, I <sub>OL</sub> = 2mA, DS = 0 (Note 1)		0.2	0.4		
GPIO P0.2, P0.3, P0.8, P0.9	V <sub>OL_I2C</sub>	V <sub>DD</sub> = 1.71V, I <sub>OL</sub> = 10mA, DS = 1 (Note 1)		0.2	0.4	V	
	Vон_дрю	V <sub>DD</sub> = 1.71V, I <sub>OH</sub> = 1mA, DS[1:0] = 00 (Note 1)	V <sub>DD</sub> - 0.4			- V	
Output High Voltage for All		V <sub>DD</sub> = 1.71V, I <sub>OH</sub> = 2mA, DS[1:0] = 10 (Note 1)	V <sub>DD</sub> - 0.4				
GPIO Except P0.2, P0.3, P0.8, and P0.9		V <sub>DD</sub> = 1.71V, I <sub>OH</sub> = 4mA, DS[1:0] = 01 (Note 1)	V <sub>DD</sub> - 0.4				
		V <sub>DD</sub> = 1.71V, I <sub>OH</sub> = 6mA, DS[1:0] = 11 (Note 1)	V <sub>DD</sub> - 0.4				
Output High Voltage for		V <sub>DD</sub> = 1.71V, I <sub>OH</sub> = 2mA, DS = 0 (Note 1)	V <sub>DD</sub> - 0.4				
GPIO P0.2, P0.3, P0.8, P0.9	V <sub>OH_I2C</sub>	V <sub>DD</sub> = 1.71V, I <sub>OH</sub> = 10mA, DS = 1 (Note 1)	V <sub>DD</sub> - 0.4			V	
Combined I <sub>OL</sub> , All GPIO	I <sub>OL_TOTAL</sub>				32	mA	
Combined I <sub>OH</sub> , All GPIO	IOH_TOTAL		-32			mA	
Input Hysteresis (Schmitt)	V <sub>IHYS</sub>			300		mV	
Input/Output Pin Capacitance for All Pins	C <sub>IO</sub>			4		pF	
Input Leakage Current Low	I <sub>IL</sub>	V <sub>IN</sub> = 0V, internal pullup disabled	-500		+500	nA	
Input Leakage Current High	I <sub>ІН</sub>	V <sub>IN</sub> = 3.6V, internal pulldown disabled	-500		+500	nA	
Input Pullup Resistor to	Rousses	Pullup to V <sub>DD</sub> = 1.62V		22		kΩ	
RSTN	R <sub>PU_VDD</sub>	Pullup to V <sub>DD</sub> = 3.63V		10.5		17.22	

## **Electrical Characteristics (continued)**

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Pullup Resistor for	Devi	Pin configured as GPIO, pullup to V <sub>DD</sub> = 1.62V		22		- kΩ
All GPIO	R <sub>PU</sub>	Pin configured as GPIO, pullup to V <sub>DD</sub> = 3.63V		10.5		
Input Pulldown Resistor for	В	Pin configured as GPIO, pulldown to $V_{SS}$ , $V_{DD} = 1.62V$		20		- kΩ
All GPIO	R <sub>PD</sub>	Pin configured as GPIO, pulldown to $V_{SS}$ , $V_{DD} = 3.63V$		8.8		K(1)
CLOCKS						
System Clock Frequency	fsys_clk		24		96	MHz
System Clock Period	tsys_clk			1/f <sub>SYS</sub> _ CLK		μs
High-Frequency Internal Oscillator (HFIO)	f <sub>HFIO</sub>	Default OVR = [10]	93.5	96	98.5	MHz
Nanoring Oscillator Frequency	f <sub>NANO</sub>			80		kHz
RTC Input Frequency	f <sub>32KIN</sub>	32.768kHz watch crystal, $C_L$ = 6pF, ESR < 90kΩ, $C_0$ < 2pF		32.768		kHz
RTC Operating Current	I <sub>RTC</sub>	All power modes, RTC enabled		0.45		μA
RTC Power-Up Time	t <sub>RTC_ON</sub>			250		ms
FLASH MEMORY						
Flash Erase Time	t <sub>M_ERASE</sub>	Mass erase		30		ms
Flasii Elase IIIIle	tp_ERASE	Page erase		30		1115
Flash Programming Time Per Word	t <sub>PROG</sub>	32-bit programming mode, f <sub>FLC_CLK</sub> = 1MHz		60		μs
Flash Endurance			10			kcycles
Data Retention	t <sub>RET</sub>	T <sub>A</sub> = +85°C	10			years

Note 1: When using a GPIO bias voltage of 2.97V, the drive current capability of the GPIO is 2x that of its drive strength when using a GPIO bias voltage of 1.62V.

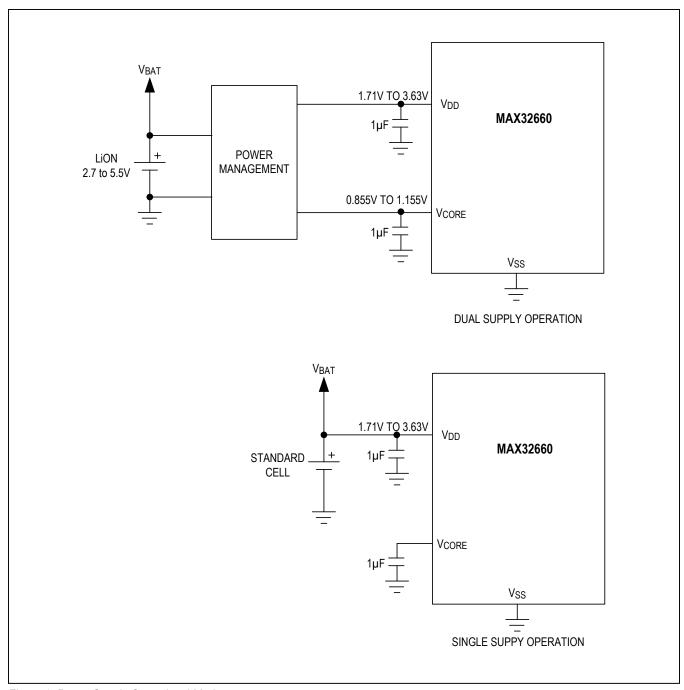


Figure 1. Power Supply Operational Modes

## **Electrical Characteristics—SPI**

(Tlming specifications are guaranteed by design and not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CONTROLLER MODE			·			
SPI Controller Operating Frequency	f <sub>MCK</sub>	f <sub>SYS_CLK</sub> = 96MHz, f <sub>MCK(MAX)</sub> = f <sub>SYS_CLK</sub> /2			48	MHz
SPI Controller SCK Period	tMCK			1/f <sub>MCK</sub>		ns
SCK Output Pulse-Width High/Low	t <sub>MCH</sub> , t <sub>MCL</sub>		t <sub>MCK</sub> /2			ns
MOSI Output Hold Time After SCK Sample Edge	tмон		t <sub>MCK</sub> /2			ns
MOSI Output Valid to Sample Edge	t <sub>MOV</sub>		t <sub>MCK</sub> /2			ns
MISO Input Valid to SCK Sample Edge Setup	t <sub>MIS</sub>			5		ns
MISO Input to SCK Sample Edge Hold	t <sub>MIH</sub>			t <sub>MCK</sub> /2		ns
TARGET MODE						•
SPI Target Operating Frequency	f <sub>SCK</sub>				48	MHz
SPI Target SCK Period	tsck			1/f <sub>SCK</sub>		ns
SCK Input Pulse-Width High/Low	t <sub>SCH</sub> , t <sub>SCL</sub>			t <sub>SCK</sub> /2		
SSx Active to First Shift Edge	t <sub>SSE</sub>			10		ns
MOSI Input to SCK Sample Edge Rise/Fall Setup	tsis			5		ns
MOSI Input from SCK Sample Edge Transition Hold	tsін			1		ns
MISO Output Valid After SCLK Shift Edge Transition	tsov			5		ns
SCK Inactive to SSx Inactive	t <sub>SSD</sub>			10		ns
SSx Inactive Time	t <sub>SSH</sub>			1/f <sub>SCK</sub>		μs
MISO Hold Time After SSx Deassertion	t <sub>SLH</sub>			10		ns

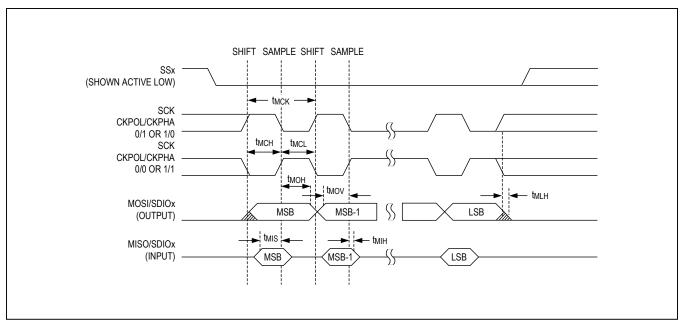


Figure 2. SPI Controller Mode Timing Diagram

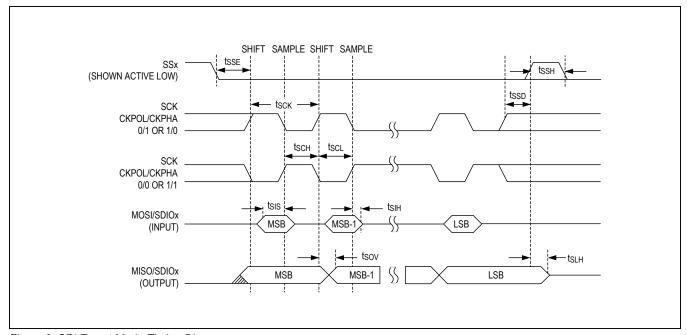


Figure 3. SPI Target Mode Timing Diagram

## Electrical Characteristics—I<sup>2</sup>C

(Limits are 100% tested at  $T_A$  = +25°C and  $T_A$  = +105°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STANDARD-MODE						
Output Fall Time	t <sub>OF</sub>	Standard mode, from V <sub>OL_I2C(MIN)</sub> to V <sub>OL_I2C(MAX)</sub>		150		ns
SCL Clock Frequency	f <sub>SCL</sub>		0		100	kHz
Low Period SCL Clock	t <sub>LOW</sub>		4.7			μs
High Time SCL Clock	t <sub>HIGH</sub>		4.0			μs
Setup Time for Repeated Start Condition	tsu;sta		4.7			μs
Hold Time for Repeated Start Condition	t <sub>HD;STA</sub>		4.0			μs
Data Setup Time	t <sub>SU;DAT</sub>			300		ns
Data Hold Time	t <sub>HD;DAT</sub>			10		ns
Rise Time for SDA and SCL	t <sub>R</sub>			800		ns
Fall Time for SDA and SCL	t <sub>F</sub>			200		ns
Setup Time for a Stop Condition	tsu;sто		4.0			μs
Bus Free Time Between a Stop and Start Condition	t <sub>BUS</sub>		4.7			μs
Data Valid Time	t <sub>VD;DAT</sub>		3.45			μs
Data Valid Acknowledge Time	t <sub>VD;ACK</sub>		3.45			μs
FAST-MODE			•			
Output Fall Time	t <sub>OF</sub>	From V <sub>OL_I2C(MIN)</sub> to V <sub>OL_I2C(MAX)</sub>		150		ns
Pulse Width Suppressed by Input Filter	t <sub>SP</sub>			75		ns
SCL Clock Frequency	f <sub>SCL</sub>		0		400	kHz
Low Period SCL Clock	t <sub>LOW</sub>		1.3			μs
High Time SCL Clock	tHIGH		0.6			μs
Setup Time for Repeated Start Condition	t <sub>SU;STA</sub>		0.6			μs
Hold Time for Repeated Start Condition	t <sub>HD;STA</sub>		0.6			μs
Data Setup Time	t <sub>SU;DAT</sub>			125		ns
Data Hold Time	t <sub>HD;DAT</sub>			10		ns
Rise Time for SDA and SCL	t <sub>R</sub>			30		ns
Fall Time for SDA and SCL	t <sub>F</sub>			30		ns
Setup Time for a Stop Condition	tsu;sto		0.6			μs

## Electrical Characteristics—I<sup>2</sup>C (continued)

(Limits are 100% tested at  $T_A$  = +25°C and  $T_A$  = +105°C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Bus Free Time Between a Stop and Start Condition	t <sub>BUS</sub>		1.3			μs
Data Valid Time	t <sub>VD;DAT</sub>		0.9			μs
Data Valid Acknowledge Time	t <sub>VD;ACK</sub>		0.9			μs
FAST-MODE PLUS						
Output Fall Time	t <sub>OF</sub>	From V <sub>OL_I2C(MIN)</sub> to V <sub>OL_I2C(MAX)</sub>		80		ns
Pulse Width Suppressed by Input Filter	t <sub>SP</sub>			75		ns
SCL Clock Frequency	f <sub>SCL</sub>		0		1000	kHz
Low Period SCL Clock	t <sub>LOW</sub>		0.5			μs
High Time SCL Clock	tHIGH		0.26			μs
Setup Time for Repeated Start Condition	<sup>t</sup> SU;STA		0.26			μs
Hold Time for Repeated Start Condition	t <sub>HD;STA</sub>		0.26			μs
Data Setup Time	t <sub>SU;DAT</sub>			50		ns
Data Hold Time	t <sub>HD;DAT</sub>			10		ns
Rise Time for SDA and SCL	t <sub>R</sub>			50		ns
Fall Time for SDA and SCL	t <sub>F</sub>			30		ns
Setup Time for a Stop Condition	tsu;sто		0.26			μs
Bus Free Time Between a Stop and Start Condition	t <sub>BUS</sub>		0.5			μs
Data Valid Time	t <sub>VD;DAT</sub>		0.45			μs
Data Valid Acknowledge Time	t <sub>VD;ACK</sub>		0.45			μs

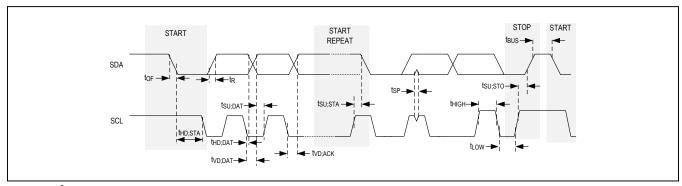


Figure 4. I<sup>2</sup>C Timing Diagram

## Electrical Characteristics—I2S Target

(Limits are 100% tested at  $T_A = +25$ °C and  $T_A = +105$ °C. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization. Specifications marked GBD are guaranteed by design and not production tested. Specifications to the minimum operating temperature are guaranteed by design and are not production tested.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Bit Clock Frequency	f <sub>BCLK</sub>	96kHz LRCLK frequency			3.072	MHz
BCLK High Time	twbclkh			0.5		1/f <sub>BCLK</sub>
BCLK Low Time				0.5		1/f <sub>BCLK</sub>
LRCLK Setup Time	tLRCLK_BLCK			25		ns
Delay Time, BCLK to SD (Output) Valid	tBCLK_SDO			12		ns
Setup Time for SD (Input)	tsu_sdi			6		ns
Hold Time SD (Input)	t <sub>HD</sub> sdi			3		ns

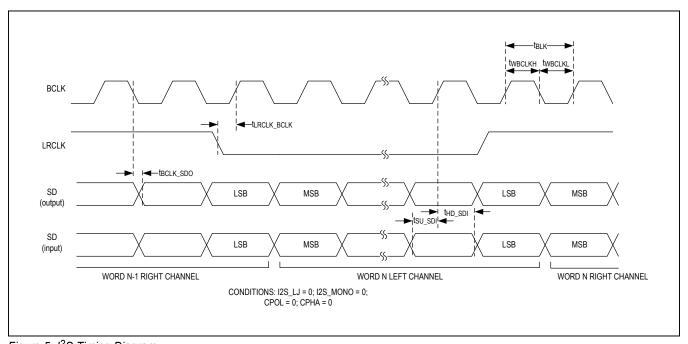
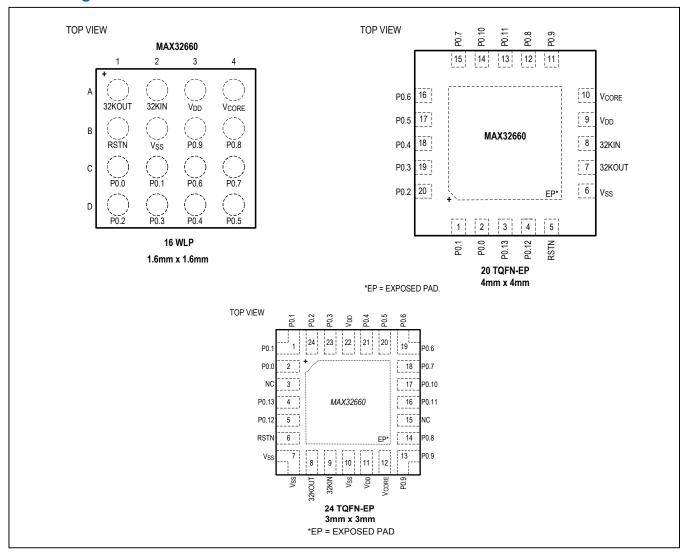


Figure 5. I<sup>2</sup>S Timing Diagram

Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

# **Pin Configurations**



## **Pin Description**

	PIN			
16 WLP		NAME	FUNCTION	
POWER				
A3	9	11, 22	V <sub>DD</sub>	Digital Supply Voltage. This pin must be bypassed to $V_{SS}$ with a $1.0\mu F$ capacitor with $60m\Omega$ to $200m\Omega$ ESR as close as possible to the package. The device can operate soley from this one power supply pin without the need to connect $V_{CORE}$ by utilizing the internal $V_{CORE}$ regulator. The internal $V_{CORE}$ regulator automatically operates if the presence of a voltage on the $V_{CORE}$ pin is not detected. This provides single supply battery operation capability.

# **Pin Description (continued)**

PIN				
16 WLP	20 TQFN- EP	24 TQFN- EP	NAME	FUNCTION
A4	10	12	V <sub>CORE</sub>	Core Supply Voltage. This pin provides dual supply operation to support PMIC-based systems and should be left open-circuit for single supply operation. This pin must always be bypassed to $V_{SS}$ with a $1.0\mu F$ capacitor with $60m\Omega$ to $200m\Omega$ ESR as close as possible to the package regardless of the supply mode of operation.
B2	6	7, 10	V <sub>SS</sub>	Digital Ground
_	_	_	EP	Exposed Pad (TQFN only). This pad must be connected to V <sub>SS</sub> . Refer to Application Note 3273: Exposed Pads: A Brief Introduction for additional information.
CLOCK				
A2	8	9	32KIN	32.768kHz Crystal Oscillator Input. Connect a 6pF 32.768kHz crystal between 32KIN and 32KOUT for RTC operation. Optionally, an external clock source can be driven on 32KIN if the 32KOUT pin is left unconnected.
A1	7	8	32KOUT	32.768kHz Crystal Oscillator Output
RESET				
B1	5	6	RSTN	Active-Low, External System Reset Input. The device remains in reset while this pin is in its active state. When the pin transitions to its inactive state, the device performs a POR reset (resetting all logic on all supplies except for real-time clock circuitry) and begins execution. This pin is internally connected with an internal pullup to the V <sub>DD</sub> supply as indicated in the <i>Electrical Characteristics</i> table. This pin should be left unconnected if the system design does not provide a reset signal to the device.
GENERAL	-PURPOSE	I/O (See Ta	ble 3 and T	able 4 for pin mapping.)
C1	2	2	P0.0	
C2	1	1	P0.1	
D1	20	24	P0.2	
D2	19	23	P0.3	
D3	18	21	P0.4	
D4	17	20	P0.5	
C3	16	19	P0.6	General-Purpose I/O. Most port pins have multiple special functions. See Table 3
C4	15	18	P0.7	and <u>Table 4</u> for details.
B4	12	14	P0.8	
В3	11	13	P0.9	
_	14	17	P0.10	
	13	16	P0.11	
_	4	5	P0.12	
	3	4	P0.13	

Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

## **Detailed Description**

The MAX32660 is an ultra-low power, cost-effective, highly-integrated microcontroller designed for battery-powered devices and wireless sensors. It combines a flexible and versatile power management unit with the powerful Arm Cortex-M4 processor with FPU. The device enables designs with complex sensor processing without compromising battery life. It also offers legacy designs an easy and cost optimal upgrade path from 8- or 16-bit microcontrollers. The device integrates up to 256KB of flash memory and 96KB of RAM to accommodate application and sensor code.

The device features four powerful and flexible power modes. It can operate from a single- or dual-supply battery voltage, typically provided by a PMIC. The I<sup>2</sup>C port supports standard, fast, fast-plus, and high-speed modes, operating up to 3400kbps. Two UARTs are provided, and the SPI ports can run up to 48MHz in both controller and target mode. Three general-purpose 32-bit timers, a watchdog timer, and a real-time clock are also provided. An I<sup>2</sup>S interface provides audio streaming to a codec.

#### Memory

#### **Internal Flash Memory**

256KB of internal flash memory provides nonvolatile storage of program and data memory.

#### **Internal SRAM**

The internal 96KB SRAM provides low-power retention of application information in all power modes except shutdown. The SRAM can be divided into granular banks that create a flexible SRAM retention architecture. This data retention feature is optional, and is configurable. This granularity allows the application to minimize its power consumption by only retaining the most essential data.

#### **Clocking Scheme**

The high-frequency internal oscillator (HFIO) operates at a nominal frequency of 96MHz.

Optionally, two other oscillators can be selected depending upon power needs:

- 80kHz nanoring oscillator
- 32.768kHz oscillator (external crystal required)

This clock is the primary clock source for the digital logic and peripherals.

An external 32.768kHz timebase is required when using the RTC.

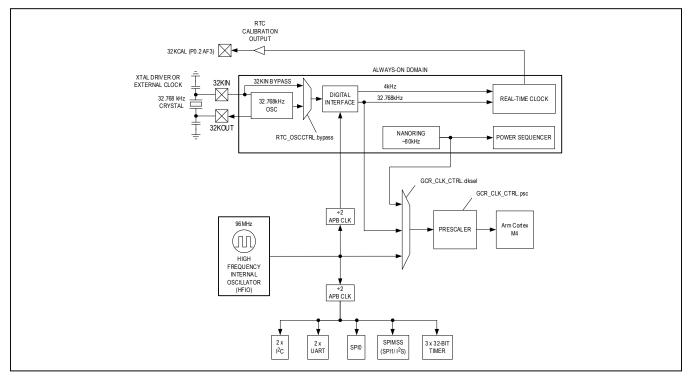


Figure 6. System Clocking Diagram

Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

#### **General-Purpose I/O and Special Function Pins**

Most general-purpose I/O (GPIO) pins share both a firmware-controlled I/O function and one or more special function signals associated with peripheral modules. Pins can be individually enabled for GPIO or peripheral special function use. Configuring a pin as a special function usually supersedes its use as a firmware-controlled I/O. Though this multiplexing between peripheral and GPIO functions is usually static, it can also be done dynamically. The electrical characteristics of a GPIO pin are identical whether the pin is configured as an I/O or special function, except where explicitly noted in the *Electrical Characteristics* tables.

In GPIO mode, each pin of a port has an interrupt function that can be independently enabled, and configured as a level- or edge-sensitive interrupt. All GPIOs share the same interrupt vector. Some packages do not have all of the GPIOs available.

When configured as GPIOs, the following features are provided. These features can be independently enabled or disabled on a per-pin basis.

- Configurable as input, output, bidirectional, or highimpedance
- Optional internal pullup resistor or internal pulldown resistor when configured as input
- Wake up from low-power modes on rising or falling edge
- Selectable standard- or high-drive modes

The MAX32660 provides up to 14 GPIOs for the 20-pin TQFN and up to 10 GPIOs for the 16-bump WLP.

#### **Standard DMA Controller**

The standard DMA (direct memory access) controller provides a means to off-load the CPU for memory/peripheral data transfer leading to a more power-efficient system. It allows automatic one-way data transfer between two entities. These entities can be either memories or peripherals. The transfers are done without using CPU resources. The following transfer modes are supported:

- 4 channel
- · Peripheral to data memory
- Data memory to peripheral
- Data memory to data memory
- Event support

All DMA transactions consist of an AHB burst read into the DMA FIFO followed immediately by an AHB burst write from the FIFO.

#### **Power Management**

#### **Power Management Unit**

The power management unit (PMU) provides high-performance operation while minimizing power consumption. It exercises intelligent, precise control of power distribution to the CPU and peripheral circuitry.

The PMU provides the following features:

- User-configurable system clock
- Automatic enabling and disabling of crystal oscillators based on power mode
- Multiple clock domains
- Fast wake-up of powered-down peripherals when activity detected

#### **Active Mode**

In this mode, the CPU is executing application code and all digital and analog peripherals are available on demand. Dynamic clocking disables peripherals not in use, providing the optimal mix of high-performance and low-power consumption.

#### Sleep Mode

This mode allows for low-power consumption operation. The CPU is asleep, peripherals are on and the standard DMA block is available. The GPIO or any active peripheral can be configured to interrupt and cause transition to the Active mode.

#### **Deep-Sleep Mode**

This mode corresponds to the Arm Cortex-M4 processor with FPU Deep-sleep mode. In this mode, the register settings and all volatile memory is preserved. The GPIO pins retain their state in this mode. The high-speed oscillator that generates the 96MHz system clock can be shut down to provide additional power savings over Sleep mode.

Multiple system events can cause the device to wake from Deep-sleep mode and return to the Active mode, including:

- RTC alarm
- Enabled GPIO interrupt

#### **Backup Mode**

This mode places the CPU in a static, low-power state. In Backup mode, all of the SRAM can be retained. Data retention in this mode is maintained by the  $V_{DD}$  supply only. SRAM retention can be 0KB, 16KB, 32KB, 64KB, or full 96KB. Backup mode supports the same wake-up sources as Deep-sleep mode.

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

#### **Real-Time Clock**

A real-time clock (RTC) keeps the time of day in absolute seconds. The 32-bit seconds register can count up to approximately 136 years and be translated to calendar format by application software.

The RTC provides a time-of-day alarm that can be programmed to any future value between 1 second and 12 days. When configured for long intervals, the time-of-day alarm can be used as a power-saving timer, allowing the device to remain in an extremely low-power mode, but still awaken periodically to perform assigned tasks. A second independent 32-bit 1/4096 subsecond alarm can be programmed between 244µs and 12 days. Both can be configured as recurring alarms. When enabled, either alarm can cause an interrupt or wake the device from most low power modes.

The time base is generated by a 32.768kHz crystal or an external clock source that must meet the electrical/timing requirements in the *Electrical Characteristics* table.

An RTC calibration feature provides the ability for user software to compensate for minor variations in the RTC oscillator, crystal, temperature, and board layout. Enabling the 32KCAL alternate function outputs a timing signal derived from the RTC. External hardware can measure the frequency and adjust the RTC frequency in increments of ±127ppm with 1ppm resolution. Under most circumstances, the oscillator does not require any calibration.

#### **Watchdog Timer**

Microcontrollers are often used in harsh environments where electrical noise and electromagnetic interference (EMI) are abundant. Without proper safeguards, these hazards can disturb device operation and corrupt program execution. One of the most effective countermeasures is the watchdog timer (WDT), which detects runaway code or system unresponsiveness.

The WDT is a 32-bit, free-running counter with a configurable prescaler. When enabled, the WDT must be periodically reset by the application software. Failure to reset the WDT within the user-configurable timeout period indicates that the application software is not operating correctly and results in a WDT timeout. A WDT timeout can trigger an interrupt, system reset, or both. Either response forces the instruction pointer to a known good location before resuming instruction execution.

The MAX32660 provides one instance of the watchdog timer (WDT0).

#### **Programmable Timers**

General-purpose, 32-bit timers provide timing, capture/compare, or generation of pulse-width modulated (PWM) signals with minimal software interaction.

The timer provides the following features:

- 32-bit up/down autoreload
- Programmable prescaler
- PWM output generation
- · Capture, compare, and capture/compare capability
- External pin multiplexed with GPIO for timer input, clock gating, or capture
- Timer output pin
- Timer interrupt

The MAX32660 provides three 32-bit timers: TMR0, TMR1, and TMR2.

I/O functionality is supported for TMR0 only (P0.3, Alternate Function 3). Note that the function of a port can be multiplexed with other functions on the GPIO pins, so it might not be possible to use all the ports depending on the device configuration.

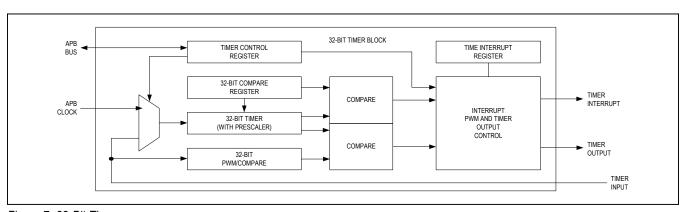


Figure 7. 32-Bit Timer

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

#### **Serial Peripherals**

#### I<sup>2</sup>C Interface

The I<sup>2</sup>C interface is a bidirectional, two-wire serial bus that provides a medium-speed communications network. It can operate as a one-to-one, one-to-many or many-to-many communications medium. These engines support Standard-mode, Fast-mode, Fast-mode Plus and High-speed mode I<sup>2</sup>C speeds. It provides the following features:

- Controller or target mode operation
  - Supports up to 4 different target addresses in target mode
- Supports standard 7-bit addressing or 10-bit addressing
- RESTART condition
- Interactive receive mode
- Transmit FIFO preloading
- Support for clock stretching to allow slower target devices to operate on higher speed busses
- Multiple transfer rates

Standard-mode: 100kbpsFast-mode: 400kbps

Fast-mode Plus: 1000kbpsHigh-speed mode: 3400kbps

- Internal filter to reject noise spikes
- · Receive FIFO depth of 8 bytes
- Transmit FIFO depth of 8 bytes

The MAX32660 provides two instances of the I<sup>2</sup>C peripheral (I2C0 and I2C1).

#### **Serial Peripheral Interface**

The serial peripheral interface (SPI) is a highly configurable, flexible, and efficient synchronous interface between multiple SPI devices on a single bus. The bus uses a single clock signal and multiple data signals, and one or more target select lines to address only the intended target device. The SPI operates independently and requires minimal processor overhead.

The provided SPI peripherals can operate in either target or controller mode and provide the following features:

- SPI modes 0, 1, 2, 3 for single-bit communication
- 3- or 4-wire mode for single-bit target device communication
- Full-duplex operation in single-bit, 4-wire mode
- Multicontroller mode fault detection
- Programmable interface timing
- Programmable SCK frequency and duty cycle
- 32-byte transmit and receive FIFOs
- Target select assertion and deassertion timing with respect to leading/trailing SCK edge

The MAX32660 provides two instances of this SPI peripheral (SPI0, SPI1) with the following specifications (Table 1):

**Table 1. SPI Configuration Options** 

INSTANCE	DATA	TARGET SELECT LINES		MAXIMUM FREQUENCY	MAXIMUM FREQUENCY	
		20 TQFN	16 WLP	(CONTROLLER MODE) (MHz)	(TARGET MODE) (MHz)	
SPI0	3 wire, 4 wire	1	1	48	48	
SPI1	3 wire, 4 wire	1	1	48	48	

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

#### I2S Interface

The I<sup>2</sup>S interface is a bidirectional, four-wire serial bus that provides serial communications for codecs and audio amplifiers compliant with the I<sup>2</sup>S Bus Specification, June 5, 1996. It provides the following features:

- Target mode operation
- Normal and left-justified data alignment
- 16-bit audio transfer
- Wake-up on FIFO status (full/empty/threshold)
- · Interrupts generated for FIFO status
- Receiver FIFO depth of 32 bytes
- Transmitter FIFO depth of 32 bytes

The MAX32660 provides one instance of the I<sup>2</sup>S peripheral that is multiplexed with the SPI1 peripheral.

#### **UART**

The universal asynchronous receiver-transmitter (UART) interface supports asynchronous communication with optional hardware flow control (HFC) modes to prevent data overruns. If HFC mode is enabled on a given port, the system uses two extra pins to implement the industry standard request to send (RTS) and clear to send (CTS) flow control signaling. Each UART is individually programmable.

- 2-wire interface or 4-wire interface with flow control
- 8-byte send/receive FIFO
- Full-duplex operation for asynchronous data transfers
- Interrupts available for frame error, parity error, CTS, Rx FIFO overrun and FIFO full/partially full conditions
- Automatic parity and frame error detection
- Independent baud-rate generator
- Programmable 9th bit parity support
- Multidrop support
- Start/stop bit support
- Hardware flow control using RTS/CTS
- Two DMA channels can be connected (read and write FIFOs)
- Programmable word size (5 bits to 8 bits)

The MAX32660 provides two instances of the UART peripheral (UART0 and UART1) with the specifications shown in Table 2.

**Table 2. UART Configuration Options** 

INSTANCE	FLOW CONTROL			
INSTANCE	20 TQFP	16 WLP		
UART0	Yes	Yes		
UART1	Yes	No		

#### **Bootloader**

Some versions of the device contain a small bootloader that resides in flash, providing the ability to update the application code by a host microcontroller. The bootloader can be accessed through the I2C, SPI, or UART interface. These interfaces provide the data channel and the control channel for communicating between the host microcontroller and the MAX32660. The bootloader application load mode is enabled and disabled by either a serial command or hardware connectivity. The serial command is interpreted by the application, which configures the device to enter the bootloader mode. When using the hardware connectivity option, a single GPIO pin and the RSTN pin on the MAX32660 can be configured to allow the MAX32660 to enter the bootloader mode. Refer to Application Note 6471: MAX32660 Bootloader User Guide for details of the bootloader operation and reserved memory locations.

#### Debug and Development Interface (SWD)

The serial wire debug interface is used for code loading and ICE debug activities. All devices in mass production have the debugging/development interface enabled.

#### **Additional Documentation and Technical Support**

Designers must have the following documents to use all the features of this device:

- This data sheet, which contains electrical/timing specifications, package information, and pin descriptions
- The corresponding revision-specific errata sheet
- The corresponding user guide, which contains detailed information and programming guidelines for core features and peripherals

## **Applications Information**

Table 3. GPIO and Alternate Function Matrix, 16 WLP

GPIO	ALTERNATE FUNCTION 1	ALTERNATE FUNCTION 2	ALTERNATE FUNCTION 3
P0.0	SWDIO**	SPI1_MISO (I2S_SDI)†	UART1_TX**
P0.1	SWDCLK**	SPI1_MOSI (I2S_SDO)†	UART1_RX**
P0.2	I2C1_SCL	SPI1_SCK (I2S_BCLK)†	32KCAL
P0.3	I2C1_SDA	SPI1_SS0 (I2S_LRCLK)†	TMR0
P0.4	SPI0_MISO	UART0_TX	_
P0.5	SPI0_MOSI	UART0_RX	_
P0.6	SPI0_SCK	UART0_CTS	UART1_TX**
P0.7	SPI0_SS0	UART0_RTS	UART1_RX**
P0.8	I2C0_SCL	SWDIO**	_
P0.9	I2C0_SDA	SWDCLK**	_
P0.10*	_	_	_
P0.11*	_	_	_
P0.12*	_	_	_
P0.13*	_	_	_

<sup>\*</sup>GPIO not pinned out.

Table 4. GPIO and Alternate Function Matrix, 20 TQFN and 24 TQFN

GPIO	ALTERNATE FUNCTION 1	ALTERNATE FUNCTION 2	ALTERNATE FUNCTION 3
P0.0	SWDIO**	SPI1_MISO (I2S_SDI)†**	UART1_TX**
P0.1	SWDCLK**	SPI1_MOSI (I2S_SDO)†**	UART1_RX**
P0.2	I2C1_SCL	SPI1_SCK (I2S_BCLK)†**	32KCAL
P0.3	I2C1_SDA	SPI1_SS0 (I2S_LRCLK)†**	TMR0
P0.4	SPI0_MISO	UART0_TX	_
P0.5	SPI0_MOSI	UART0_RX	_
P0.6	SPI0A_SCK	UART0_CTS	UART1_TX**
P0.7	SPI0A_SS0	UART0_RTS	UART1_RX**
P0.8	I2C0_SCL	SWDIO**	
P0.9	I2C0_SDA	SWDCLK**	_
P0.10	SPI1_MISO (I2S_SDI)†**	UART1_TX	_
P0.11	SPI1_MOSI (I2S_SDO)†**	UART1_RX	_
P0.12	SPI1_SCK (I2S_BCLK)†**	UART1_CTS	<u> </u>
P0.13	SPI1_SS0 (I2S_LRCLK)†**	UART1_RTS	_

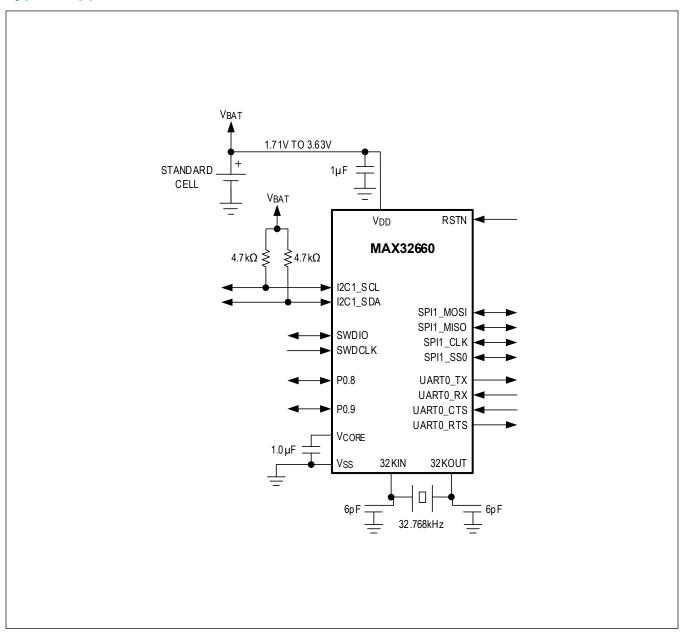
<sup>\*\*</sup>This signal can be mapped to more than one GPIO, but there is only one instance of this peripheral.

<sup>\*\*</sup>This signal can be mapped to more than one GPIO, but there is only one instance of this peripheral.

<sup>†</sup>These pins support I<sup>2</sup>S functionality. Refer to the User Guide for details.

<sup>†</sup>I2S\_BCLK, I2S\_LRCLK, I2S\_SDI, I2S\_SDO when enabled.

# **Typical Application Circuit**



Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

# **Ordering Information**

PART	FLASH (KB)	SRAM (KB)	BOOT- LOADER	PIN-PACKAGE
MAX32660GWE+	256	96	No	16 WLP (1.6mm x 1.6mm x 0.65mm, 0.35mm pitch)
MAX32660GWE+T	256	96	No	16 WLP (1.6mm x 1.6mm x 0.65mm, 0.35mm pitch)
MAX32660GTP+	256	96	No	20 TQFN-EP (4mm x 4mm x 0.75mm, 0.5mm pitch)
MAX32660GTP+T	256	96	No	20 TQFN-EP (4mm x 4mm x 0.75mm, 0.5mm pitch)
MAX32660GTG+	256	96	No	24 TQFN-EP (3mm x 3mm x 0.75mm, 0.4mm pitch)
MAX32660GTG+T	256	96	No	24 TQFN-EP (3mm x 3mm x 0.75mm, 0.4mm pitch)
MAX32660GWEBL+	256	96	Yes	16 WLP (1.6mm x 1.6mm x 0.65mm, 0.35mm pitch)
MAX32660GWEBL+T	256	96	Yes	16 WLP (1.6mm x 1.6mm x 0.65mm, 0.35mm pitch)
MAX32660GTGBL+	256	96	Yes	24 TQFN-EP (3mm x 3mm x 0.75mm, 0.4mm pitch)
MAX32660GTGBL+T	256	96	Yes	24 TQFN-EP (3mm x 3mm x 0.75mm, 0.4mm pitch)
MAX32660e/d+	256	96	Yes	Bare die. Contact factory for details.

<sup>+</sup>Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel. Full reel.

# Tiny, Ultra-Low-Power Arm Cortex-M4 Processor with FPU-Based Microcontroller (MCU) with 256KB Flash and 96KB SRAM

## **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	1/18	Initial release	_
1	4/18	Updated General Description, Applications, Benefits and Features, Absolute Maximum Ratings, Package Information, Electrical Characteristics table, Pin Configurations, Pin Descriptions, Table 4 title, Ordering Information, and added Typical Application Circuit	1, 3, 8, 15, 16, 22–24
2	6/18	Updated Simplified Block Diagram, Electrical Characteristics table, Figure 1, Figure 2, Figure 3, Clocking Scheme section, Figure 6, and Ordering Information table	2, 4–6, 8–10, 11, 17, 24
3	8/18	Updated Ordering Information	24
4	8/18	Updated Ordering Information	24
5	10/18	Updated title and General Description	1–25
6	12/18	Updated Ordering Information	24
7	2/19	Updated title, General Description, Pin Configuration, Ordering Information, Additional Documentation and Technical Support, and added Bootloader section	1–25
8	9/19	Updated Benefits and Features, Simplified Block Diagram, Electrical Characteristics table, Clocking Scheme, Figure 6, Real-Time Clock, UART, Table 4	1, 2, 4–6, 8, 17, 19, 21, 22
9	6/22	Updated Benefits and Features, Simplified Block Diagram, and Absolute Maximum Ratings. Replaced all occurrences of "master" with "controller" and all instances of "slave" with "target". Updated the VDD and VCORE pin descriptions to add bypass capacitor ESR requirement. Updated the RSTN pin description. Updated the Detailed Description section introduction. Updated Figure 6. Updated the Programmable Timers section. Updated Bootloader section with reserved memory information. Removed all mention of UART maximum baud rate. Updated Typical Application Circuit. Updated the Ordering Information table.	1–3, 10–21, 23, 24

