

Quad DC/DC μ Module Regulator with Configurable 1.2A Output Array

FEATURES

- Quad Output Step-Down μ Module® Regulator with 1.2A per Output Channel
- Wide Input Voltage Range: 2.7V to 17V
- 0.6V to 5.5V Output Voltage
- 1.2A DC, Parallelable, Output Current Each Channel
- $\pm 1.5\%$ Total Output Voltage Regulation
- 100% Duty Cycle Operation
- Current Mode Control, Fast Transient Response
- External Frequency Synchronization
- Selectable Burst Mode® Operation
- Power Good Indicator
- Over Voltage, Current and Temperature Protection
- 6.25mm $\times$ 6.25mm $\times$ 2.1mm BGA Package
- Pin Compatible with LTM4668 (0.6V to 1.8V Output, 1MHz).

APPLICATIONS

- Telecom, Networking and Industrial Equipment
- Multi-Rail Point of Load Regulation
- FPGAs, DSPs and ASICs Application

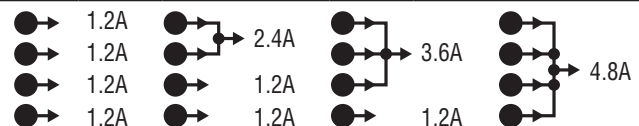
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DESCRIPTION

The **LTM®4668A** is a quad DC/DC step-down μ Module (micromodule) regulator with 1.2A DC current per output. Outputs can be paralleled in an array for up to 4.8A capability. Included in the package are the switching controllers, power FETs, inductors and support components. Operating over an input voltage range of 2.7V to 17V, the LTM4668A supports an output voltage range of 0.6V to 5.5V. Only bulk input and output capacitors are needed. The device supports frequency synchronization, PolyPhase operation, selectable Burst Mode operation, 100% duty cycle and low I_Q operation. Its high switching frequency and a current mode architecture enables a very fast transient response to line and load changes without sacrificing stability.

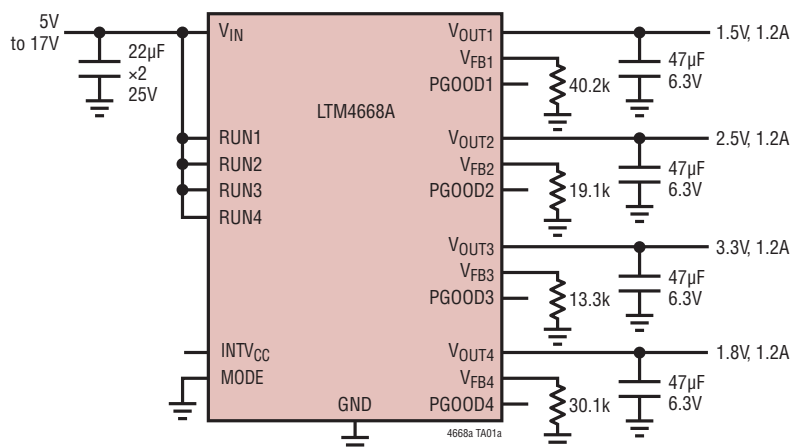
Fault protection features include overvoltage, overcurrent and overtemperature protection. The power module is offered in a space saving and thermally enhanced 6.25mm $\times$ 6.25mm $\times$ 2.1mm BGA package. The LTM4668A is available with SnPb (BGA) or RoHS-compliant terminal finish.

Configurable Output Array

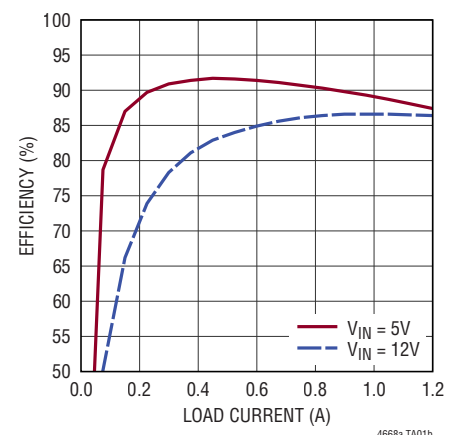


TYPICAL APPLICATION

5V to 17V Input, Quad 1.5V, 1.8V, 2.5V, 3.3V Output DC/DC μ Module Regulator



3.3V Output Efficiency (Each Channel)



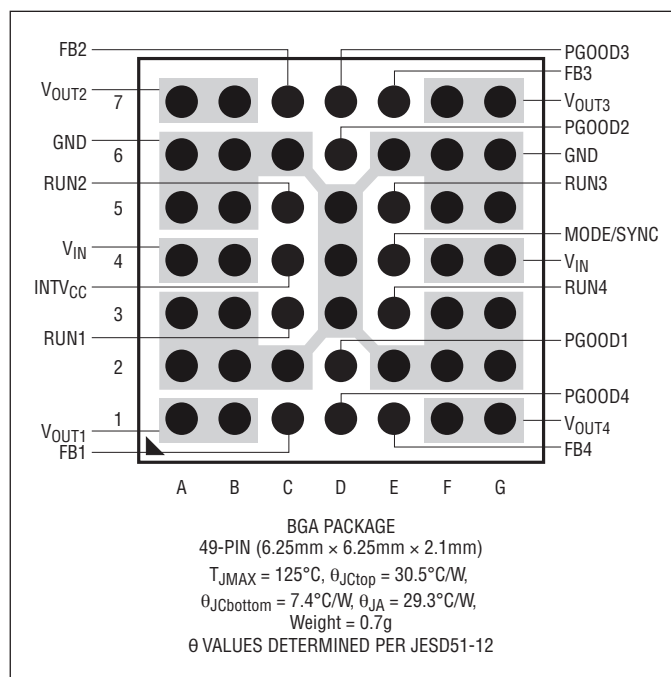
LTM4668A

ABSOLUTE MAXIMUM RATINGS

(Note 1)

V_{IN}	–0.3V to 17V
V_{OUT} (per Channel)	–0.3V to 6V
RUN (per Channel)	–0.3V to 17V
PGOOD (per Channel)	–0.3V to 6V
FB (per Channel)	–0.3V to $INTV_{CC}$
MODE/SYNC	–0.3V to $INTV_{CC} + 0.3V$
Operating Junction Temperature (Note 2) ..	–40 to 125°C
Storage Temperature Range	–55 to 125°C
Peak Solder Reflow Body Temperature	260°C

PIN CONFIGURATION



ORDER INFORMATION

PART NUMBER	PAD OR BALL FINISH	FINISH CODE	PACKAGE TYPE	MSL RATING	TEMPERATURE RANGE (SEE NOTE 2)
LTM4668AEY#PBF	SAC305 (RoHS)	e1	BGA	4	–40°C to 125°C
LTM4668AIY#PBF	SAC305 (RoHS)	e1	BGA	4	–40°C to 125°C
LTM4668AIY	SnPb (63/37)	e0	BGA	4	–40°C to 125°C

- Device temperature grade is indicated by a label on the shipping container.
- Pad or ball finish code is per IPC/JEDEC J-STD-609.
- [BGA Package and Tray Drawings](#)
- This product is not recommended for second side reflow. This product is moisture sensitive. For more information, go to [Recommended BGA PCB Assembly and Manufacturing Procedures](#).

ELECTRICAL CHARACTERISTICS The ● denotes the specifications which apply over the specified internal operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. $V_{IN} = 12\text{V}$, per the typical application.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Switching Regulator Section: (Per Channel)							
V_{IN}	Input DC Voltage		●	2.7		17	V
$V_{OUT(RANGE)}$	Output Voltage Range	$V_{IN} = 2.7\text{V}$ to 17V (Step-Down Only)	●	0.6		5.5	V
$V_{OUT(DC)}$	Output Voltage, Total Variation with Line and Load	$C_{IN} = 10\mu\text{F}$, $C_{OUT} = 47\mu\text{F}$ Ceramic, $R_{FB} = 13.3\text{k}$, $\text{MODE} = \text{INTV}_{CC}/2$, $V_{IN} = 5\text{V}$ to 17V , $I_{OUT} = 0\text{A}$ to 1.2A	●	3.25	3.30	3.35	V
V_{RUN}	RUN Pin On Threshold	V_{RUN} Rising		0.35	0.7	0.9	V
$I_{Q(VIN)}$	Input Supply Bias Current	$V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$, $\text{MODE} = \text{INTV}_{CC}/2$ (CCM) $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$, $\text{MODE} = \text{INTV}_{CC}$ (Burst) $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$, $\text{MODE} = \text{GND}$ (PS) Shutdown, $RUN = 0$, $V_{IN} = 12\text{V}$			75 0.5 200 1		 mA mA μA μA
$I_{S(VIN)}$	Input Supply Current	$V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$, $I_{OUT} = 1.2\text{A}$			390		mA
$I_{OUT(DC)}$	Output Continuous Current Range	$V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$ (Note 4)		0		1.2	A
$\frac{\Delta V_{OUT}(\text{Line})}{V_{OUT}}$	Line Regulation Accuracy	$V_{OUT} = 3.3\text{V}$, $V_{IN} = 5\text{V}$ to 17V , $I_{OUT} = 0\text{A}$	●		0.01	0.1	%/V
$\frac{\Delta V_{OUT}(\text{Load})}{V_{OUT}}$	Load Regulation Accuracy	$V_{OUT} = 3.3\text{V}$, $I_{OUT} = 0\text{A}$ to 1.2A	●		0.1	0.75	%
$V_{OUT(AC)}$	Output Ripple Voltage	$I_{OUT} = 0\text{A}$, $C_{OUT} = 47\mu\text{F}$ Ceramic, $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$			8		mV
$\Delta V_{OUT(START)}$	Turn-On Overshoot	$I_{OUT} = 0\text{A}$, $C_{OUT} = 47\mu\text{F}$ Ceramic, $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$			30		mV
t_{START}	Turn-On Time	$C_{OUT} = 47\mu\text{F}$ Ceramic, $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$, No Load			0.8		ms
ΔV_{OUTLS}	Peak Deviation for Dynamic Load	Load: 0% to 50% to 0% of Full Load, $C_{OUT} = 47\mu\text{F}$ Ceramic, $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$			70		mV
t_{SETTLE}	Settling Time for Dynamic Load Step	Load: 0% to 50% to 0% of Full Load, $C_{OUT} = 47\mu\text{F}$ Ceramic, $V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$			30		μs
I_{OUTPK}	Output Current Limit	$V_{IN} = 12\text{V}$, $V_{OUT} = 3.3\text{V}$			2		A
V_{FB}	Voltage at V_{FB} Pin	$I_{OUT} = 0\text{A}$, $V_{OUT} = 3.3\text{V}$	●	0.591	0.60	0.609	V
I_{FB}	Current at V_{FB} Pin	(Note 3)				±10	nA
R_{FBHI}	Resistor Between V_{OUT} and V_{FB} Pins			60.05	60.40	60.75	kΩ
$t_{ON(MIN)}$	Minimum On-Time	(Note 5)			60		ns

ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the specified internal operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. $V_{IN} = 12\text{V}$, per the typical application.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V_{PGOOD}	PGOOD Trip Level	V_{FB} With Respect to Set Output V_{FB} Ramping Negative V_{FB} Ramping Positive	-12	-7.5 7.5	12	% %
R_{PGOOD}	PGOOD Resistance			275		Ω
V_{INTVCC}	Internal V_{CC} Voltage	$V_{IN} = 6\text{V}$ to 17V	4.7	5	5.3	V
UVLO	Undervoltage Lockout	V_{IN} Ramping Up	2.3	2.5	2.7	V
UVLO(HYS)	UVLO Hysteresis			250		mV
f_{OSC}	Oscillator Frequency			2.25		MHz
SYNC	SYNC Capture Range		1500		3000	kHz

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: The LTM4668A is tested under pulsed load conditions such that $T_J \approx T_A$. The LTM4668AE is guaranteed to meet performance specifications over the 0°C to 125°C internal operating temperature range. Specifications over the full -40°C to 125°C internal operating temperature range are assured by design, characterization and correlation

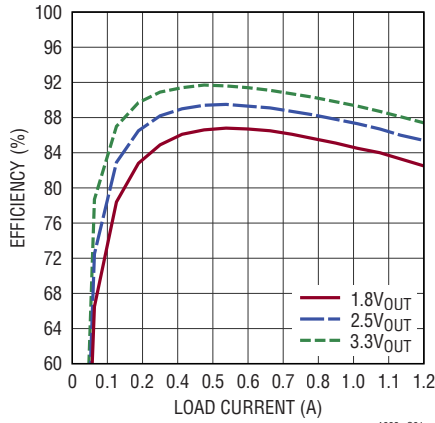
with statistical process controls. The LTM4668AI is guaranteed to meet specifications over the full -40°C to 125°C internal operating temperature range. Note that the maximum ambient temperature consistent with these specifications is determined by specific operating conditions in conjunction with board layout, the rated package thermal resistance and other environmental factors.

Note 3: 100% tested at wafer level

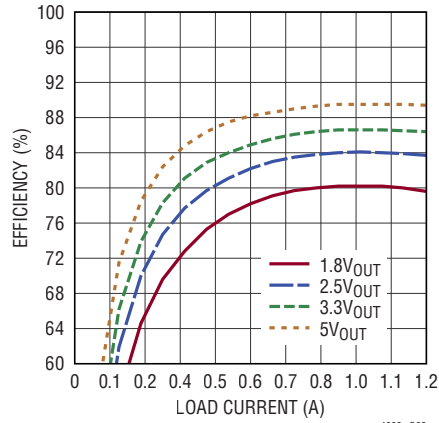
Note 4: See Thermal Considerations and Output Current Derating for different V_{IN} , V_{OUT} and T_A .

Note 5: Guaranteed by design.

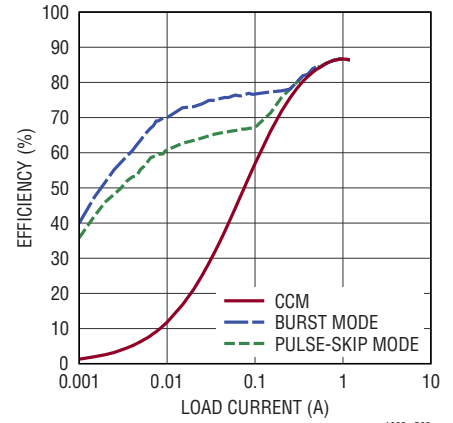
TYPICAL PERFORMANCE CHARACTERISTICS

Efficiency vs Load Current at 5V_{IN}

4668a G01

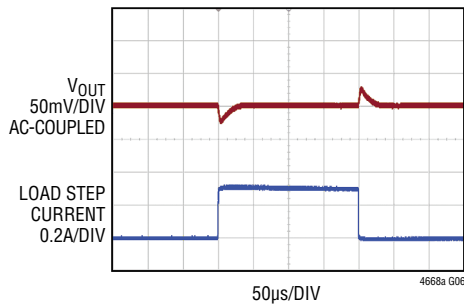
Efficiency vs Load Current at 12V_{IN}

4668a G02

CCM, Burst and Pulse Skip Mode Efficiency V_{IN} = 12V, V_{OUT} = 3.3V

4668a G03

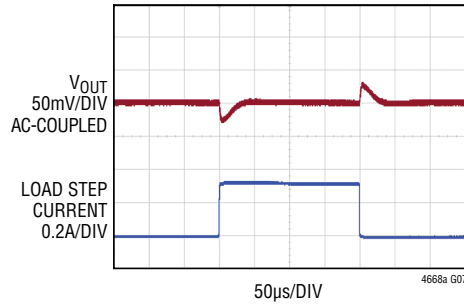
1.8V Output Transient Response



4668a G06

V_{IN} = 12V, V_{OUT} = 1.8V, f_S = 2.25MHz
 C_{OUT} = 1× 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF
 0.3A LOAD STEP 10A/μA

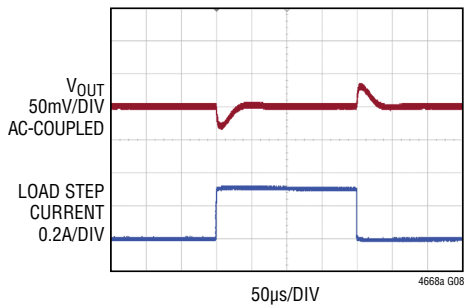
2.5V Output Transient Response



4668a G07

V_{IN} = 12V, V_{OUT} = 2.5V, f_S = 2.25MHz
 C_{OUT} = 1× 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF
 0.3A LOAD STEP 10A/μA

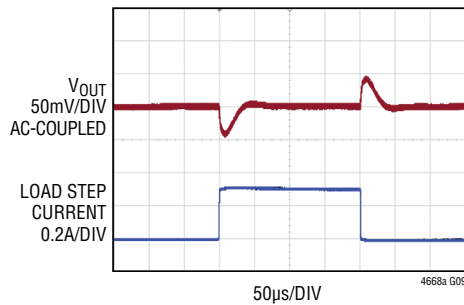
3.3V Output Transient Response



4668a G08

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz
 C_{OUT} = 1× 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF
 0.3A LOAD STEP 10A/μA

5V Output Transient Response

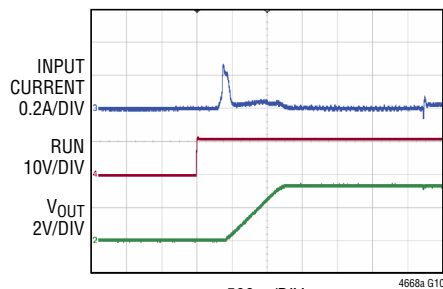


4668a G09

V_{IN} = 12V, V_{OUT} = 5V, f_S = 2.25MHz
 C_{OUT} = 1× 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF
 0.3A LOAD STEP 10A/μA

TYPICAL PERFORMANCE CHARACTERISTICS

Start-Up Waveform without Load Current

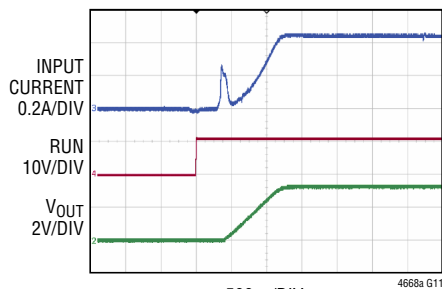


500μs/DIV

4668a G10

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz
 C_{OUT} = 1 × 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF

Start-Up Waveform with 1.2A Load Current

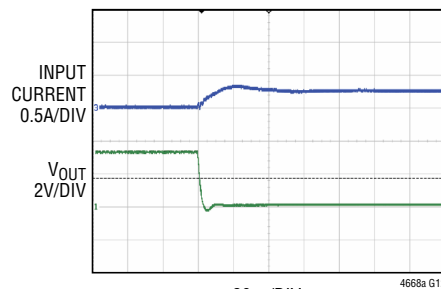


500μs/DIV

4668a G11

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz
 C_{OUT} = 1 × 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF

Output Short-Circuit Waveform without Load Applied

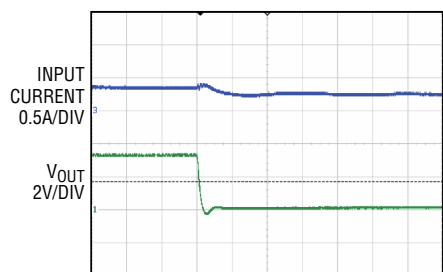


20μs/DIV

4668a G12

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz
 C_{OUT} = 1 × 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF

Output Short-Circuit Waveform with 1.2A Load Current Applied

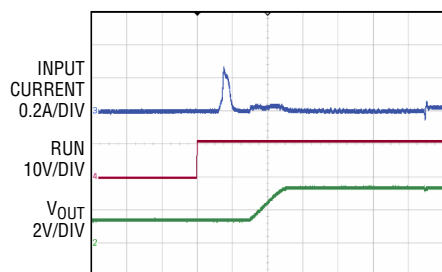


20μs/DIV

4668a G13

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz
 C_{OUT} = 1 × 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF

Start-Up into Pre-Biased Output

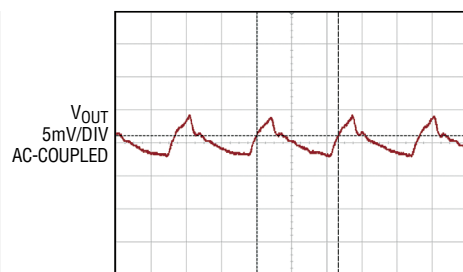


500μs/DIV

4668a G14

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz,
 OUTPUT PREBIASED TO 1.5V
 C_{OUT} = 1 × 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF

Steady-State Output Voltage Ripple



500ns/DIV

4668a G15

V_{IN} = 12V, V_{OUT} = 3.3V, f_S = 2.25MHz
 C_{OUT} = 1 × 47μF CERAMIC CAPACITOR
 C_{FF} = 150pF

PIN FUNCTIONS

V_{OUT1} (A1, B1), V_{OUT2} (A7, B7), V_{OUT3} (F7, G7), V_{OUT4} (F1, G1): Power Output Pins of each switching mode regulator channel. Apply output load between these pins and GND pins. Recommend placing output decoupling capacitance directly between these pins and GND pins. See the Applications Information section for paralleling outputs.

GND (A2–A3, A5–A6, B2–B3, B5–B6, C2, C6, D3–D5, E2, E6, F2–F3, F5–F6, G2–G3, G5–G6): Power Ground Pins for both Input and Output Returns. Use large PCB copper areas to connect all GND together.

V_{IN} (A4, B4, F4, G4): Power Input Pins connect to the drain of the internal top MOSFET for each switching mode regulator channel and the internal 5V regulator for the control circuitry. Apply input voltages between these pins and GND pins. Recommend placing input decoupling capacitance directly between each of V_{IN} pins and GND pins.

FB1 (C1), FB2 (C7), FB3 (E7), FB4 (E1): The Negative Input of the Error Amplifier for each switching mode regulator channel. Internally, this pin is connected to V_{OUT} of each channel with a 60.4k Ω precision resistor. Different output voltages can be programmed with an additional resistor between FB and GND pins. In PolyPhase[®] operation, connect FB pins for all slave channels to INTV_{CC} and connect V_{OUT} for all paralleled channels together. See the Applications Information section for details.

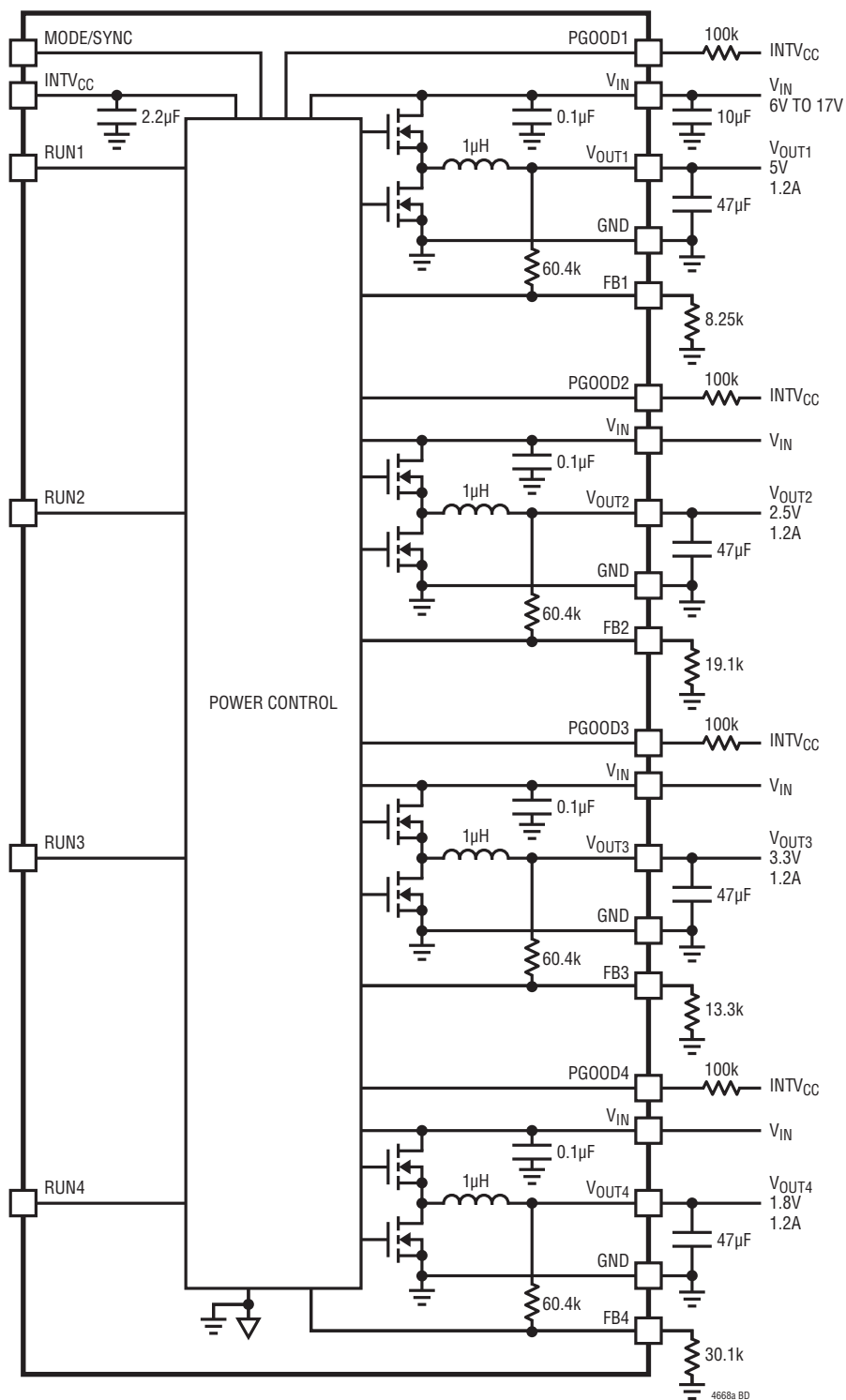
PGOOD1 (D2), PGOOD2 (D6), PGOOD3 (D7), PGOOD4 (D1): Output Power Good with Open-Drain Logic of each switching mode regulator channel. PGOOD is pulled to ground when the voltage on the FB pin is not within $\pm 7.5\%$ of the internal 0.6V reference.

RUN1 (C3), RUN2 (C5), RUN3 (E5), RUN4 (E3): Run Control Input of each switching mode regulator channel. Enable regulator operation by tying the specific RUN pin above 1V. Tying it below 0.35V shuts down the specific regulator channel.

INTV_{CC} (C4): Internal 5V Regulator Output. The internal power drivers and control circuits are powered from this voltage. Decouple each pin to GND with a minimum of 2.2 μ F local low ESR ceramic capacitor. INTV_{CC} only starts up if at least one of the RUN pins is high.

MODE/SYNC (E4): Burst Mode Select and External Clock Synchronization of the switching mode regulator. Tie MODE/SYNC to INTV_{CC} for Burst Mode operation with a 400mA peak current clamp. Tie MODE/SYNC to GND for pulse-skipping operation, and tie MODE/SYNC to a voltage between 1V and INTV_{CC} – 1.2V for forced continuous mode. Furthermore, connecting this pin to an external clock will synchronize the switch clock to the external clock and put the part in forced continuous mode. Do not float this pin.

BLOCK DIAGRAM



DECOUPLING REQUIREMENTS

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Switching Regulator Section: (Per Channel)						
C _{IN}	External Input Capacitor Requirement (V _{IN} = 2.7V to 17V, V _{OUT} = 1.5V)	I _{OUT} = 1.2A	4.7	10		μF
C _{OUT}	External Output Capacitor Requirement (V _{IN} = 2.7V to 17V, V _{OUT} = 1.5V)	I _{OUT} = 1.2A	22	47		μF

OPERATION

The LTM4668A is a quad output standalone non-isolated switch mode DC/DC power supply. It has built-in four separate regulator channels and each of them can deliver 1.2A continuous output current with few external input and output capacitors. Each regulator provides precisely regulated output voltage programmable via a single external resistor over 2.7V to 17V input voltage range. The LTM4668A supports output voltages of 0.6V to 5.5V. The typical application schematic is shown in Figure 14.

The LTM4668A uses a constant frequency, peak current mode architecture and has integrated power MOSFETs, inductors, and other supporting discrete components. The typical switching frequency is set to 2.25MHz. For switching noise-sensitive applications, the μModule can be externally synchronized to a clock from 1.5MHz to 3MHz. See the Applications Information section.

With current mode control and internal feedback loop compensation, the LTM4668A module has sufficient stability margins and good transient performance with a wide range of output capacitors, even with all ceramic output capacitors.

Current mode control provides the flexibility of paralleling any of the separate regulator channels with accurate current sharing. With a built-in clock interleaving between each two regulator channels, the LTM4668A could easily employ a 2+2, 3+1 or all 4 channels, parallel operation which is more than flexible in a multi-rail POL application.

Current mode control also provides cycle-by-cycle fast overcurrent protection. An internal overvoltage and undervoltage comparator pulls the open-drain PGOOD output low if the output feedback voltage exits a $\pm 7.5\%$ window around the regulation point. Furthermore, in an overvoltage condition, internal top FET is turned off and bottom FET is turned on and held on until the overvoltage condition clears.

Pulling the RUN pin below 0.35V forces the controller into its shutdown state, turning off both power MOSFETs and most of the internal control circuitry. At light load currents, pulse-skipping mode or Burst Mode operation can be enabled to achieve higher efficiency compared to continuous mode (CCM) by setting MODE/SYNC pin to GND or INTV_{CC} accordingly. The LTM4668A has internal 800μs soft-start ramp on each output channel.

The pin compatible part LTM4668 is recommended when operating at a lower output voltage range of 0.6V to 1.8V and has a typical switching frequency of 1MHz. The differences between LTM4668 and LTM4668A are shown in Table 1.

Table 1. Recommended Part Selection

	RECOMMENDED V _{OUT} RANGE	SWITCHING FREQUENCY
LTM4668	0.6V to 1.8V	1MHz
LTM4668A	0.6V to 5.5V*	2.25MHz

*There are restrictions in the maximum V_{IN} and V_{OUT} step-down ratio. See V_{IN} to V_{OUT} Step-Down Ratios section.

APPLICATIONS INFORMATION

The typical LTM4668A application circuit is shown in Figure 14. External component selection is primarily determined by the input voltage, the output voltage and the maximum load current. Refer to Table 8 for specific external capacitor requirements for a particular application.

V_{IN} to V_{OUT} Step-Down Ratios

There are restrictions in the maximum V_{IN} and V_{OUT} step-down ratio that can be achieved for a given input voltage due to the minimum on-time limits of each regulator channel. The minimum on-time limit imposes a minimum duty cycle of the converter which can be calculated as:

$$D_{MIN} = T_{ON(MIN)} \cdot f_{SW}$$

where $T_{ON(MIN)}$ is the minimum on-time, 60ns typical for LTM4668A.

In the cases where the minimum duty cycle is surpassed, pulse-skipping mode (MODE/SYNC = GND) or Burst Mode (MODE/SYNC = INTV_{CC}) has to be implemented instead of forced continuous mode operation in order to allow the LTM4668A to decrease switching frequency and maintain output voltage in regulation. The pin compatible module LTM4668 can also be used in high V_{IN} , low V_{OUT} application to avoid minimum on time violation with its 1MHz default switching frequency.

The LTM4668A is able to run at 100% duty cycle operation. As the duty cycle approaches 100%, the LTM4668A enters dropout operation. During dropout, the top PMOS switch is turned on continuously, and all active circuitry is kept alive.

Note that additional thermal derating may be applied. See the Thermal Considerations and Output Current Derating section in this data sheet.

Output Voltage Programming

The PWM controller has an internal 0.6V reference voltage. As shown in the Block Diagram, a 60.4k 0.5% internal feedback resistor connects each regulator channel V_{OUT} and FB pin together. Adding a resistor R_{FB} from FB pin to GND programs the output voltage:

$$V_{OUT} = 0.6V \cdot \frac{60.4k + R_{FB}}{R_{FB}}$$

Table 2. V_{FB} Resistor Table vs Various Output Voltages

$V_{OUT}(V)$	0.6	1.0	1.2	1.5	1.8	2.5	3.3	5.0
$R_{FB}(k)$	OPEN	90.9	60.4	40.2	30.1	19.1	13.3	8.25

For parallel operation, a single resistor as determined by the previous equation is used for R_{FB} and is connected from a master channel's FB pin to GND. Tie the FB pins of the slave channels to INTV_{CC} and tie the V_{OUT} pins and the RUN pins together for all channels in parallel. See the Multi-Channel Parallel Operation section.

Input Decoupling Capacitors

The LTM4668A module should be connected to a low AC-impedance DC source. One piece of 4.7μF input ceramic capacitor is required to be placed on each side of the module for RMS ripple current decoupling. Bulk input capacitor is only needed when the input source impedance is compromised by long inductive leads, traces or not enough source capacitance. The bulk capacitor can be an electrolytic aluminum capacitor and polymer capacitor.

Without considering the inductor current ripple, the RMS current of the input capacitor can be estimated as:

$$I_{CIN(RMS)} = \frac{I_{OUT(MAX)}}{\eta\%} \cdot \sqrt{D \cdot (1-D)}$$

where $\eta\%$ is the estimated efficiency of the power module.

Output Decoupling Capacitors

With an optimized high frequency, high bandwidth design, only single piece of low ESR output ceramic capacitor is required for each regulator channel to achieve low output voltage ripple and very good transient response. Additional output filtering may be required by the system designer, if further reduction of output ripples or dynamic transient spikes is required. Table 8 shows a matrix of different output voltages and output capacitors to minimize the voltage droop and overshoot during a 0.3A (25%) load step transient. Multiphase operation will reduce effective output ripple as a function of the number of phases. [Application Note 77](#) discusses this noise reduction versus output ripple current cancellation, but the output capacitance will be more a function of stability and transient response. The [LTpowerCAD®](#) design tool is available to download online

APPLICATIONS INFORMATION

for output ripple, stability and transient response analysis and calculating the output ripple reduction as the number of phases implemented increases by N times.

Burst Mode Operation

The LTM4668A is capable of Burst Mode operation in which the power MOSFETs operate intermittently based on load demand, thus saving quiescent current. For applications where maximizing the efficiency at very light loads is a high priority, Burst Mode operation should be applied. To enable Burst Mode operation, simply tie the MODE/SYNC pin to INTV_{CC}.

During Burst Mode operation, the peak current of the inductor is set to approximately 400mA in normal operation even though the output of the error amplifier (COMP) indicates a lower value. The COMP voltage drops when the inductor's average current is greater than the load requirement. As the COMP voltage drops below 0.2V, the burst comparator trips, causing the internal sleep line to go high and turn off both power MOSFETs.

In sleep mode, the internal circuitry is partially turned off, reducing the quiescent current. The load current is now being supplied from the output capacitors. When the output voltage drops, causing COMP voltage to rise, the internal sleep line goes low, and the LTM4668A resumes normal operation. The next oscillator cycle will turn on the top power MOSFET and the switching cycle repeats.

When all channels are in sleep mode, the LTM4668A module draws only 8μA of quiescent current from V_{IN}.

Pulse-Skipping Mode Operation

In applications where low output ripple and high efficiency at intermediate currents are desired, pulse-skipping mode should be used by grounding the MODE/SYNC pin. In LTM4668A, pulse-skipping mode is implemented similarly to Burst Mode operation with the peak inductor current set to be at least 66mA. This results in lower ripple than in Burst Mode operation with the trade-off of slightly lower efficiency.

Both modes, Burst Mode operation and pulse-skipping mode, automatically switch from continuous operation to the selected mode when the load current is low.

Forced Continuous Current Mode (CCM)

In applications where fixed frequency operation is more critical than low current efficiency, and where the lowest output ripple is desired, forced continuous operation should be used. Forced continuous operation can be enabled by tying the MODE pin to INTV_{CC}/2. In this mode, inductor current is allowed to reverse during low output loads, the output of the error amplifier is in control of the current comparator threshold throughout, and the top MOSFET always turns on with each oscillator pulse.

During start-up, the module operates in pulse-skipped mode regardless of the mode programmed on the MODE/SYNC pin to prevent inductor current from reversing until the LTM4668A's output voltage is in regulation.

Operating Frequency

The operating frequency of the LTM4668A is optimized to achieve the compact package size and the minimum output ripple voltage while keeping high efficiency. The default operating frequency is internally set to 2.25MHz. In most applications, no additional frequency adjusting is required.

If any operating frequency other than 2.25MHz is required by application, the μModule can be externally synchronized to a clock from 1.5MHz to 3MHz.

Frequency Synchronization and Clock In

The power module has a phase-locked loop comprised of an internal voltage controlled oscillator and a phase detector. This allows all internal top MOSFET turn-on to be locked to the rising edge of the same external clock. The external clock frequency range must be within ±50% around the 2.25MHz set frequency. A pulse detection circuit is used to detect a clock on the MODE/SYNC pin to turn on the phase-locked loop. The pulse width of the clock has to be at least 400ns. The clock high level must be above 2V and clock low level below 0.3V. During the start-up of the regulator, the phase-locked loop function is disabled. And once engaged in frequency sync, the LTM4668A runs in forced continuous mode at the external clock frequency.

APPLICATIONS INFORMATION

Multi-Channel Parallel Operation

For the application that demands more than 1.5A of output current, the LTM4668A multiple regulator channels can be easily paralleled to provide more output current without increasing input and output voltage ripples. The LTM4668A has preset built-in 180° phase shift between channel 1, 2 and 3, 4 which is suitable to employ a 2+2, 3+1 or 4 channel parallel operation. Table 3 gives the phase difference between regulator channels.

Table 3. Phase Difference Between Regulator Channels

CHANNEL	CH1	CH2	CH3	CH4
Phase Diff.	0°	180°	0°	

Figure 1 shows a 2+2 and a 4-channels parallel concept schematics for clock phasing.

A multiphase power supply significantly reduces the amount of ripple current in both the input and output capacitors. The RMS input ripple current is reduced by, and the effective ripple frequency is multiplied by, the number of phases used (assuming that the input voltage is greater than the number of phases used times the output voltage). The output ripple amplitude is also reduced by the number of phases used when all of the outputs are tied together to achieve a single high output current design.

The LTM4668A device is an inherently current mode controlled device, so parallel modules will have very good current sharing. This will balance the thermals on the design. When configuring the LTM4668A for parallel operation, channels 1 and 4 serve as master channels to slave channels 2 and 3, respectively. To configure a channel as a slave, tie its FB pin to INTV_{CC} to shut down

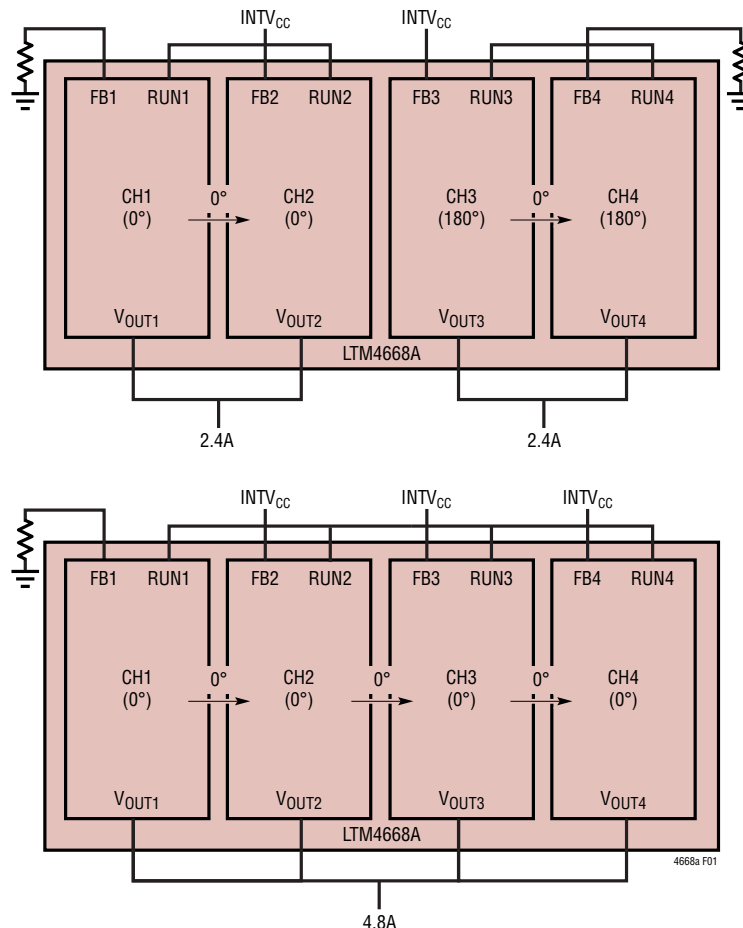


Figure 1. 2+2 and 4-Channel Parallel Concept Schematic

APPLICATIONS INFORMATION

its control circuitry. The master channel's drive signal is used instead to drive the slave channel's power switches. Then, to complete configuration, tie its V_{OUT} to the master channel V_{OUT} and its RUN pin to the master channel's RUN pin. Channel 2 and 3 cannot be tied together to provide a dual channel single output. For a three-channel single-output, or four-channel single-output, channel 1 is used as the master channel. Table 4 lists the recommended channel combinations for multi-channel parallel operation. In parallel output application, use the master channel's PGGOOD signal as the power good indicator. Do not tie PGGOOD pins together.

Table 4. Configuration of Multi-Channel Parallel Operation

NUMBER OF OUTPUT VOLTAGE RAILS	PARALLELING CHANNEL	MASTER CHANNEL	PGOOD INDICATOR
QUAD	1/2/3/4		
TRIPLE	(1+2)/3/4	1	PGOOD1
DUAL	(1+2)/(3+4)	1, 4	PGOOD1, 4
DUAL	(1+2+4)/3	1	PGOOD1
SINGLE	(1+2+3+4)	1	PGOOD1

Input RMS Ripple Current Cancellation

[Application Note 77](#) provides a detailed explanation of multiphase operation. The input RMS ripple current cancellation mathematical derivations are presented, and a graph is displayed representing the RMS ripple current reduction as a function of the number of interleaved phases. Figure 2 shows this graph.

Soft-Start and Output Voltage Tracking

The LTM4668A has an internal 800 μ s soft-start ramp for each channel. During soft-start operation, the switcher operates in pulse-skipping mode regardless of the mode programmed on the MODE/SYNC pin. Once the soft-start period is complete, the part will transition into the desired mode of operation.

Power Good

The PGGOOD pins are open drain pins that can be used to monitor valid output voltage regulation. This pin monitors

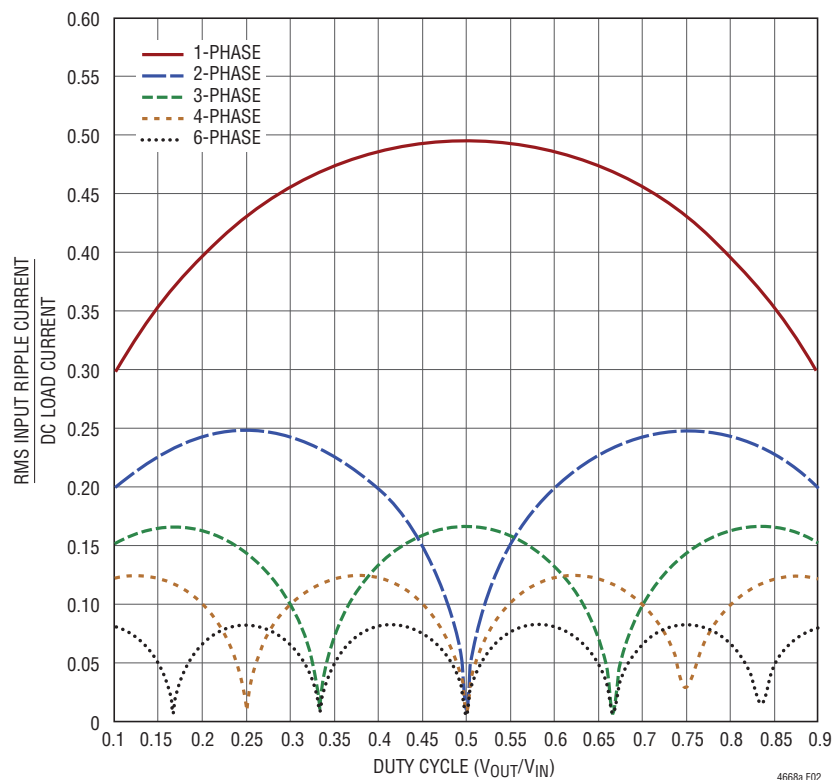


Figure 2. Input RMS Current Ratios to DC Load Current as a Function of Duty Cycle

APPLICATIONS INFORMATION

a $\pm 7.5\%$ window around the regulation point. A resistor can be pulled up to a particular supply voltage for monitoring. To prevent unwanted PGOOD glitches during transients or dynamic V_{OUT} changes, the LTM4668A's PGOOD falling edge includes a blanking delay of approximately 32 switching cycles.

Stability Compensation

The LTM4668A module internal compensation loop of each regulator channel is designed and optimized for low ESR ceramic output capacitors only application. Table 6 is provided for most application requirements. In cases that require bulk output capacitors for output ripple or dynamic transient spike reduction, an additional 10pF to 15pF phase boost cap is recommended between V_{OUT} and FB pins. The LTpowerCAD design tool is available to download for control loop optimization.

Run Enable

Pulling the RUN pin of each regulator channel to ground forces the regulator into its shutdown state, turning off both power MOSFETs and most of its internal control circuitry. Bringing the RUN pin above 1V will turn on the entire regulator channel.

V_{IN} Overvoltage Protection

The LTM4668A module constantly monitors the V_{IN} pins for an overvoltage condition. When V_{IN} rises above 19V, the corresponding regulator suspends operation by shutting off both power MOSFETs. Once V_{IN} drops below 18.7V, the regulator immediately resumes normal operation. The regulators execute soft-start function when exiting an overvoltage condition.

Thermal Considerations and Output Current Derating

The thermal resistances reported in the Pin Configuration section of the data sheet are consistent with those parameters defined by JESD51-9 and are intended for use with finite element analysis (FEA) software modeling tools that leverage the outcome of thermal modeling, simulation and correlation to hardware evaluation performed on a μ Module package mounted to a hardware test board—also defined by JESD51-9 (“Test Boards for Area Array

Surface Mount Package Thermal Measurements”). The motivation for providing these thermal coefficients in found in JESD51-12 (“Guidelines for Reporting and Using Electronic Package Thermal Information”).

Many designers may opt to use laboratory equipment and a test vehicle such as the demo board to anticipate the μ Module regulator's thermal performance in their application at various electrical and environmental operating conditions to compliment any FEA activities. Without FEA software, the thermal resistances reported in the Pin Configuration section are in-and-of themselves not relevant to providing guidance of thermal performance; instead, the derating curves provided in the data sheet can be used in a manner that yields insight and guidance pertaining to one's application usage, and can be adapted to correlate thermal performance to one's own application.

The Pin Configuration section typically gives four thermal coefficients explicitly defined in JESD51-12; these coefficients are quoted or paraphrased below:

1. θ_{JA} , the thermal resistance from junction to ambient, is the natural convection junction-to-ambient air thermal resistance measured in a one cubic foot sealed enclosure. This environment is sometimes referred to as “still air” although natural convection causes the air to move. This value is determined with the part mounted to a JESD51-9 defined test board, which does not reflect an actual application or viable operating condition.
2. $\theta_{JCbottom}$, the thermal resistance from junction to the bottom of the product case, is determined with all of the component power dissipation flowing through the bottom of the package. In the typical μ Module regulator, the bulk of the heat flows out the bottom of the package, but there is always heat flow out into the ambient environment. As a result, this thermal resistance value may be useful for comparing packages, but the test conditions don't generally match the user's application.
3. θ_{JCtop} , the thermal resistance from junction to top of the product case, is determined with nearly all of the component power dissipation flowing through the top of the package. As the electrical connections of the typical μ Module are on the bottom of the package, it

APPLICATIONS INFORMATION

is rare for an application to operate such that most of the heat flows from the junction to the top of the part. As in the case of $\theta_{JCbottom}$, this value may be useful for comparing packages but the test conditions don't generally match the user's application.

4. θ_{JB} , the thermal resistance from junction to the printed circuit board, is the junction-to-board thermal resistance where almost all of the heat flows through the bottom of the μ Module and into the board, and is really the sum of the $\theta_{JCbottom}$ and the thermal resistance of the bottom of the part through the solder joints and through a portion of the board. The board temperature is measured a specified distance from the package, using a two sided, two layer board. This board is described in JESD51-9.

A graphical representation of the aforementioned thermal resistances is given in Figure 3; blue resistances are contained within the μ Module regulator, whereas green resistances are external to the μ Module.

As a practical matter, it should be clear to the reader that no individual or sub-group of the four thermal resistance parameters defined by JESD51-12 or provided in the Pin Configuration section replicates or conveys normal operating conditions of a μ Module. For example, in normal board-mounted applications, never does 100% of the device's total power loss (heat) thermally conduct exclusively through the top or exclusively through bottom of the μ Module—as the standard defines for θ_{JCtop} and

$\theta_{JCbottom}$, respectively. In practice, power loss is thermally dissipated in both directions away from the package—granted, in the absence of a heat sink and airflow, a majority of the heat flow is into the board.

Within a SIP (system-in-package) module, be aware there are multiple power devices and components dissipating power, with a consequence that the thermal resistances relative to different junctions of components or die are not exactly linear with respect to total package power loss. To reconcile this complication without sacrificing modeling simplicity—but also, not ignoring practical realities—an approach has been taken using FEA software modeling along with laboratory testing in a controlled-environment chamber to reasonably define and correlate the thermal resistance values supplied in this data sheet: (1) Initially, FEA software is used to accurately build the mechanical geometry of the μ Module and the specified PCB with all of the correct material coefficients along with accurate power loss source definitions; (2) this model simulates a software-defined JEDEC environment consistent with JESD51-9 to predict power loss heat flow and temperature readings at different interfaces that enable the calculation of the JEDEC-defined thermal resistance values; (3) the model and FEA software is used to evaluate the μ Module with heat sink and airflow; (4) having solved for and analyzed these thermal resistance values and simulated various operating conditions in the software model, a thorough laboratory evaluation replicates the simulated conditions with thermocouples within a controlled-environment

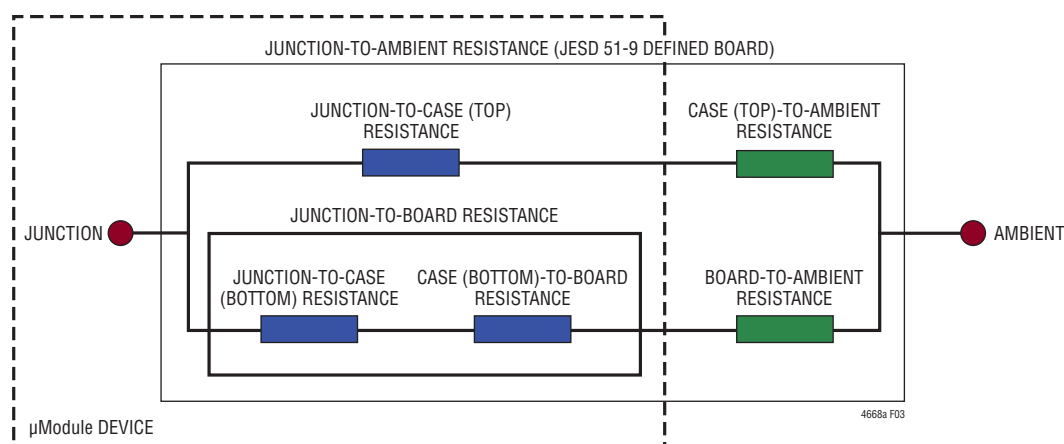


Figure 3. Graphical Representation of JESD51-12 Thermal Coefficients

APPLICATIONS INFORMATION

chamber while operating the device at the same power loss as that which was simulated. An outcome of this process and due-diligence yields a set of derating curves provided in other sections of this data sheet. After these laboratory test have been performed and correlated to the μ Module model, then the θ_{JB} and θ_{BA} are summed together to correlate quite well with the μ Module model with no airflow or heat sinking in a properly define chamber. This $\theta_{JB} + \theta_{BA}$ value is shown in the Pin Configuration section and should accurately equal the θ_{JA} value because approximately 100% of power loss flows from the junction through the board into ambient with no airflow or top mounted heat sink.

The 1.8V, 3.3V and 5V power loss curves in Figures 4 to 6 can be used in coordination with the load current derating curves in Figures 7 to 12 for calculating an approximate θ_{JA} thermal resistance for the LTM4668A with various airflow conditions. The power loss curves are taken at room temperature, and are increased with multiplicative factors of 1.3 considering both MOSFET $R_{DS(ON)}$ and inductor DCR increases at 120°C junction temperature when the derating starts. The derating curves are plotted with the output current starting at 4.8A with all 4 channels paralleled together and the ambient temperature at 40°C. The output voltages are 1.8V, 3.3V and 5V. These are chosen to include the lower and higher output voltage ranges for correlating the thermal resistance. Thermal models are derived from several temperature measurements in a controlled temperature chamber along with thermal modeling analysis. The junction temperatures are monitored while ambient temperature is increased with and without airflow. The power loss increase with ambient temperature change is factored into the derating curves. The junctions

are maintained at 120°C maximum while lowering output current or power with increasing ambient temperature. The decreased output current will decrease the internal module loss as ambient temperature is increased. The monitored junction temperature of 120°C minus the ambient operating temperature specifies how much module temperature rise can be allowed.

As an example, in Figure 11 the load current is derated to ~3.75A at ~80°C with no air or heat sink and the power loss for the 12V to 3.3V at 3.75A output is about 2.6W. The 2.6W loss is calculated with the ~2W room temperature loss from the 12V to 3.3V power loss curve at 3.75A, and the 1.3 multiplying factor at 125°C junction. If the 80°C ambient temperature is subtracted from the 120°C junction temperature, then the difference of 40°C divided by 2.6W equals a 15.3°C/W θ_{JA} thermal resistance. Table 5 specifies a 15°C/W value which is very close.

Table 5 to Table 7 provide equivalent thermal resistances for 1.8V, 3.3V and 5V outputs with and without airflow. The derived thermal resistances in Table 5 and Table 6 for the various conditions can be multiplied by the calculated power loss as a function of ambient temperature to derive temperature rise above ambient, thus maximum junction temperature. Room temperature power loss can be derived from the efficiency curves in the Typical Performance Characteristics section and adjusted with the above ambient temperature multiplicative factors. The printed circuit board is a 1.6mm thick six layer board with two ounce copper for the two outer layers and one ounce copper for the four inner layers. The PCB dimensions are 94mm × 100mm.

APPLICATIONS INFORMATION

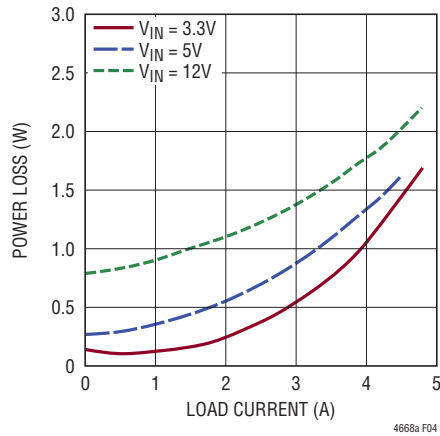


Figure 4. 1.8V Output Power Loss

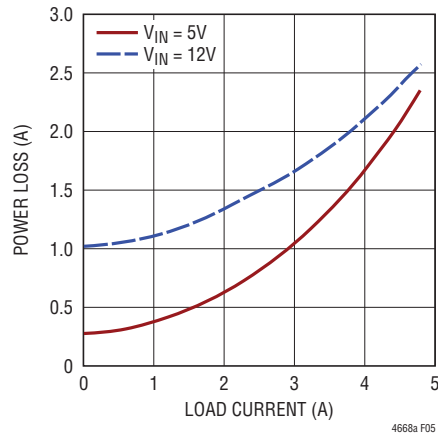


Figure 5. 3.3V Output Power Loss

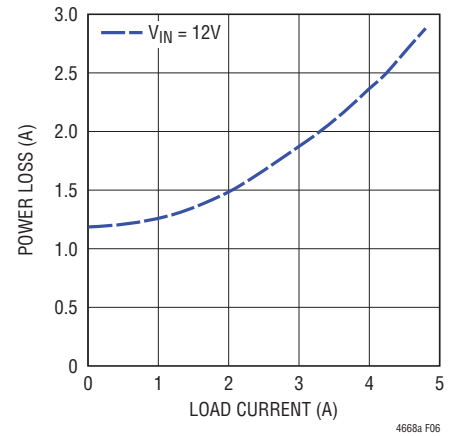


Figure 6. 5V Output Power Loss

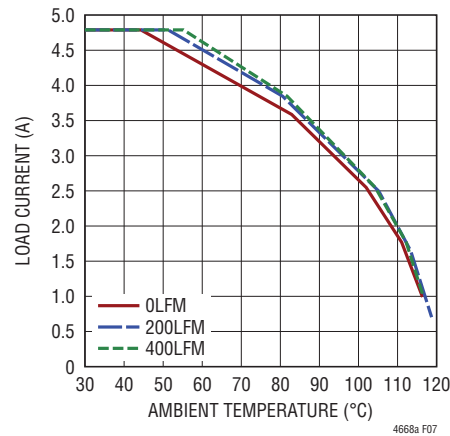


Figure 7. 3.3V to 1.8V Derating Curve, No Heat Sinking

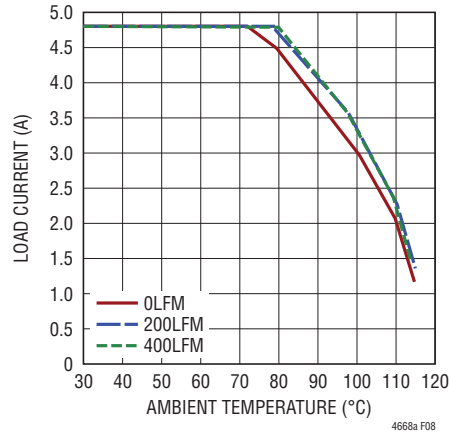


Figure 8. 5V to 1.8V Derating Curve, No Heat Sinking

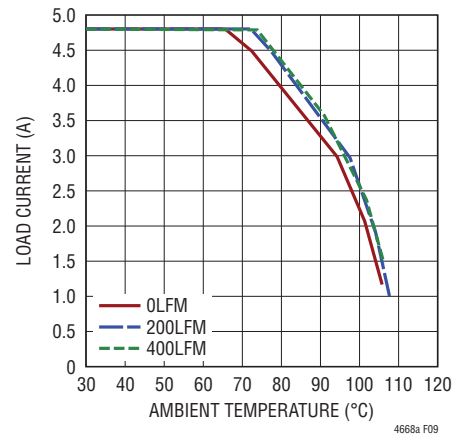


Figure 9. 12V to 1.8V Derating Curve, No Heat Sinking

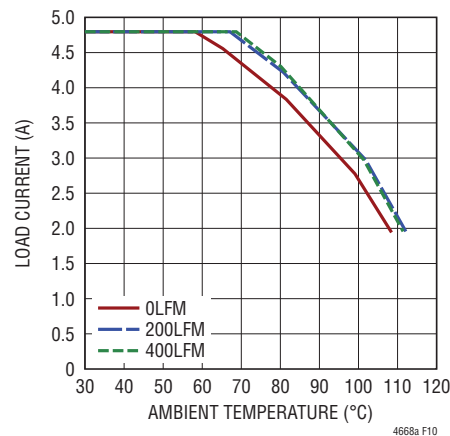


Figure 10. 5V to 3.3V Derating Curve, No Heat Sinking

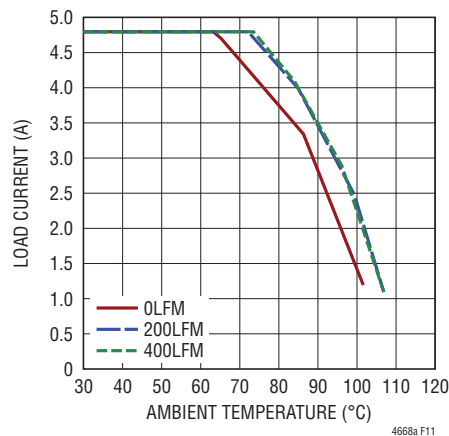


Figure 11. 12V to 3.3V Derating Curve, No Heat Sinking

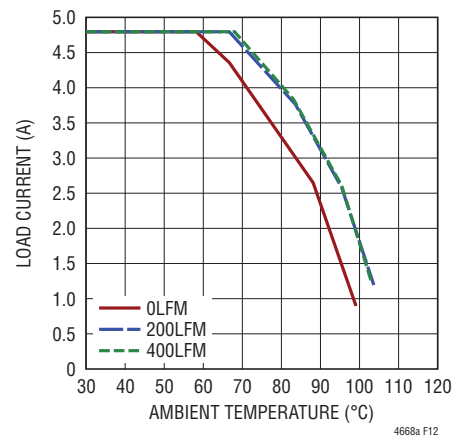


Figure 12. 12V to 5V Derating Curve, No Heat Sinking

APPLICATIONS INFORMATION

Table 5. 1.8V Output

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W)
Figures 7, 8, 9	3.3, 5, 12	Figure 4	0	None	15
Figures 7, 8, 9	3.3, 5, 12	Figure 4	200	None	13
Figures 7, 8, 9	3.3, 5, 12	Figure 4	400	None	12

Table 6. 3.3V Output

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W)
Figures 10, 11	5, 12	Figure 5	0	None	15
Figures 10, 11	5, 12	Figure 5	200	None	13
Figures 10, 11	5, 12	Figure 5	400	None	12

Table 7. 5V Output

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W)
Figure 12	12	Figure 6	0	None	15
Figure 12	12	Figure 6	200	None	13
Figure 12	12	Figure 6	400	None	12

Table 8. Output Voltage Response vs Component Matrix (Refer to Figure 14) 0A to 0.3A Load Step Typical Measured Values

C _{IN} CERAMIC VENDORS	VALUE	PART NUMBER	C _{OUT} CERAMIC VENDORS	VALUE	PART NUMBER
MURATA	22μF, 25V	GRM21BR61E226ME44L	MURATA	47μF, 6.3V	GRM21BR60J476ME15
TAIYO YUDEN	22μF, 25V	TMK316BBJ226ML-T	TAIYO YUDEN	47μF, 6.3V	JMK212BJ476MG-T

V _{OUT} (V)	C _{IN} (CERAMIC)	C _{IN} (BULK)	C _{OUT1} (CERAMIC)	C _{OUT2} (BULK)	C _{FF} (pF)	V _{IN} (V)	DROOP (mV)	P-P DERIVATION (mV)	RECOVERY TIME (μs)	LOAD STEP (A)	LOAD STEP SLEW RATE (A/μs)	RFB (kΩ)
1.8	20μF	NA	47μF	NA	150	5, 12	0	56	30	0.3	10	30.1
2.5	20μF	NA	47μF	NA	150	5, 12	0	61	35	0.3	10	19.1
3.3	20μF	NA	47μF	NA	150	5, 12	0	68	40	0.3	10	13.3
5	20μF	NA	47μF	NA	150	12	0	92	50	0.3	10	8.25
1	20μF	NA	47μF	NA	150	5	0	48.2	13	0.3	10	90.9
1.2	20μF	NA	47μF	NA	150	5	0	48.9	15	0.3	10	60.4
1.5	20μF	NA	47μF	NA	150	5	0	51.5	20	0.3	10	40.2

APPLICATIONS INFORMATION

Safety Considerations

The LTM4668A modules do not provide galvanic isolation from V_{IN} to V_{OUT} . There is no internal fuse. If required, a slow blow fuse with a rating twice the maximum input current needs to be provided to protect each unit from catastrophic failure. The device does support thermal shutdown and overcurrent protection.

Layout Checklist/Example

The high integration of LTM4668A makes the PCB board layout very simple and easy. However, to optimize its electrical and thermal performance, some layout considerations are still necessary.

- Use large PCB copper areas for high current paths, including V_{IN} , GND, V_{OUT1} and V_{OUT2} . It helps to minimize the PCB conduction loss and thermal stress.
- Place high frequency ceramic input and output capacitors next to the V_{IN} , PGND and V_{OUT} pins to minimize high frequency noise.

- Place a dedicated power ground layer underneath the unit.
- To minimize the via conduction loss and reduce module thermal stress, use multiple vias for interconnection between top layer and other power layers.
- Do not put vias directly on the pad, unless they are capped or plated over.
- Use a separated SGND ground copper area for components connected to signal pins. Connect the SGND to GND underneath the unit.
- For parallel operation, tie the V_{OUTS} and RUNs together, and the subordinate channels are connected to $INTV_{CC}$. See Figure 1 for explanation.
- Bring out test points on the signal pins for monitoring.

Figure 13 gives a good example of the recommended layout.

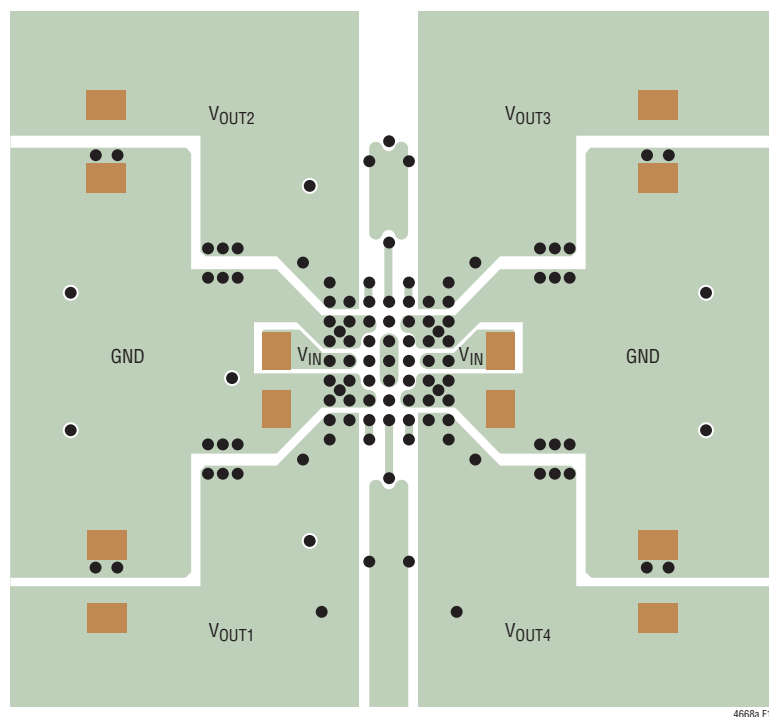


Figure 13. Recommended PCB Layout

TYPICAL APPLICATIONS

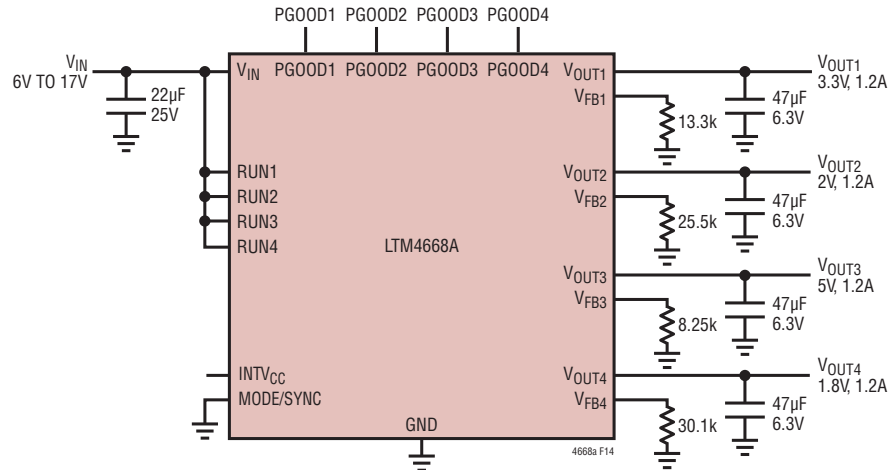


Figure 14. 6V to 17V Input, 3.3V, 2V, 5V, 1.8V Output at 1.2A Design

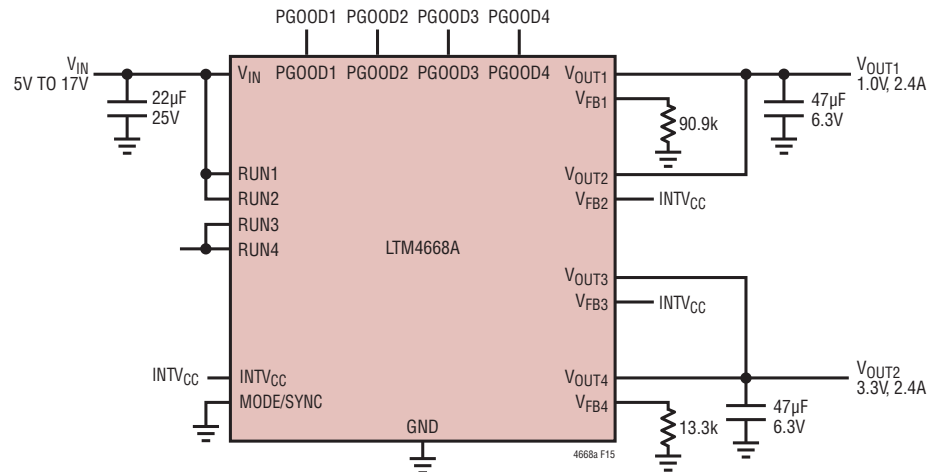


Figure 15. 5V to 17V Input, 1V and 3.3V Output at 2.4A Design with Pulse-Skipping Mode

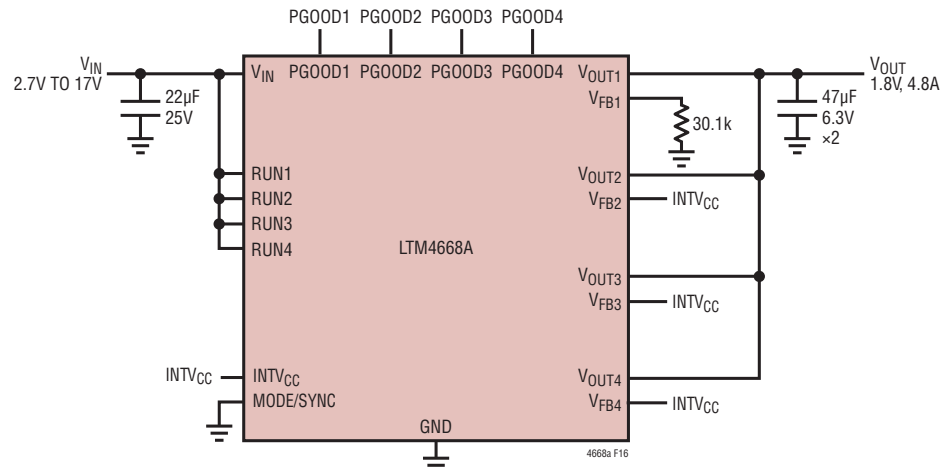


Figure 16. 2.7V to 17V Input, Four Phase Parallel Single Output 1.8V at 4.8A Design

PACKAGE DESCRIPTION



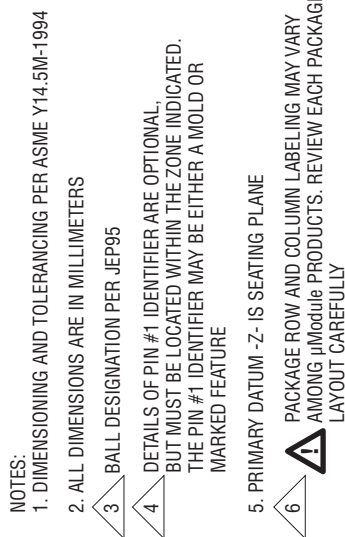
PACKAGE ROW AND COLUMN LABELING MAY VARY
AMONG μ Module PRODUCTS. REVIEW EACH PACKAGE
LAYOUT CAREFULLY.

Table 9. LTM4668A Component BGA Pinout

PIN	NAME	PIN	NAME	PIN	NAME	PIN	NAME	PIN	NAME	PIN	NAME	PIN	NAME
A1	V _{OUT1}	B1	V _{OUT1}	C1	FB1	D1	PGOOD4	E1	FB4	F1	V _{OUT4}	G1	V _{OUT4}
A2	GND	B2	GND	C2	GND	D2	PGOOD1	E2	GND	F2	GND	G2	GND
A3	GND	B3	GND	C3	RUN1	D3	GND	E3	RUN4	F3	GND	G3	GND
A4	V _{IN}	B4	V _{IN}	C4	INTV _{CC}	D4	GND	E4	MODE/SYNC	F4	V _{IN}	G4	V _{IN}
A5	GND	B5	GND	C5	RUN2	D5	GND	E5	RUN3	F5	GND	G5	GND
A6	GND	B6	GND	C6	GND	D6	PGOOD2	E6	GND	F6	GND	G6	GND
A7	V _{OUT2}	B7	V _{OUT2}	C7	FB2	D7	PGOOD3	E7	FB3	F7	V _{OUT3}	G7	V _{OUT3}

For more information www.analog.com

(Reference LTC DWG# 05-08-1600 Rev 0)

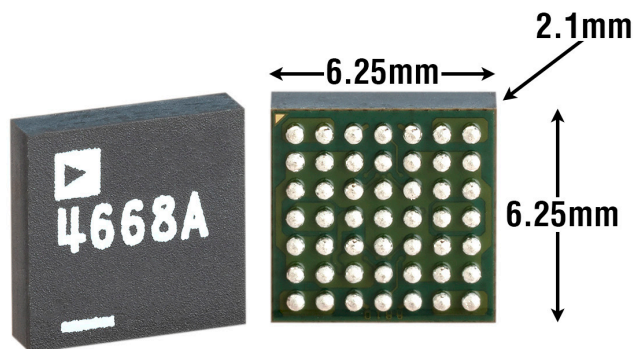


REVISION HISTORY

REV	DATE	DESCRIPTION	PAGE NUMBER
A	02/20	Added ground symbol to Typical Application schematics.	1
		MODE/SYNC pin description: Added "Do not float this pin".	7
		INTV _{CC} pin description: Added "INTV _{CC} only starts up if at least one of the RUN pins is high".	7
		Added clarification on V _{IN} to V _{OUT} step-down ratio on LTM466A.	9
		Added clarification on PGOOD in multi-channel applications.	13
		Table 5: Added 3 more lines for V _{OUT} = 1V, 1.2V, 1.5V.	18
		Edited Figure 14 and 15.	20
		Edited Figure 16.	21
B	08/21	Edited description of $\theta_{JCbottom}$ on Thermal Considerations and Output Current Derating.	14
C	05/22	Updated Part Marking in the Order Information table.	2
		Added ink marking statement to package photos.	24
D	2/24	Updated RUN Pin On Threshold range (PCN 23_0160).	3
		Updated Electrical Characteristics, Note 4.	4
		Updated PGOOD Trip Level range (PCN 23_0160).	4
		Reorganized Pin Functions alphanumerically.	7
		Updated Table 1 Title.	9
		Minimum on-time corrected from 40ns to 60ns.	10
		Layout Checklist/Example for parallel operation updated.	19
E	1/25	Added LTM4668AIY to the Order Information table.	2

PACKAGE PHOTOS

Part marking is either ink mark or laser mark



DESIGN RESOURCES

SUBJECT	DESCRIPTION	
µModule Design and Manufacturing Resources	Design: • Selector Guides • Demo Boards and Gerber Files • Free Simulation Tools	Manufacturing: • Quick Start Guide • PCB Design, Assembly and Manufacturing Guidelines • Package and Board Level Reliability
µModule Regulator Products Search	1. Sort table of products by parameters and download the result as a spread sheet. 2. Search using the Quick Power Search parametric table.	
Digital Power System Management	Analog Devices' family of digital power supply management ICs are highly integrated solutions that offer essential functions, including power supply monitoring, supervision, margining and sequencing, and feature EEPROM for storing user configurations and fault logging.	

RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTM4668	Quad 1.2A Step-Down µModule Regulator	$2.7V \leq V_{IN} \leq 17V$, $0.6V \leq V_{OUT} \leq 1.8V$, 6.25mm × 6.25mm × 2.1mm BGA
LTM4622	Ultrathin, Dual 2.5A or Single 5A Step-Down µModule Regulator	$3.6V \leq V_{IN} \leq 20V$, $0.6V \leq V_{OUT} \leq 5.5V$, 6.25mm × 6.25mm × 1.82mm LGA, 6.25mm × 6.25mm × 2.42mm BGA
LTM4622A	Higher V_{OUT} of LTM4622	$3.6V \leq V_{IN} \leq 20V$, $1.2V \leq V_{OUT} \leq 12V$, 6.25mm × 6.25mm × 1.82mm LGA, 6.25mm × 6.25mm × 2.42mm BGA
LTM4623	Ultrathin, Single 3A Step-Down µModule Regulator	$4V \leq V_{IN} \leq 20V$, $0.6V \leq V_{OUT} \leq 5.5V$, 6.25mm × 6.25mm × 1.82mm LGA, 6.25mm × 6.25mm × 2.42mm BGA
LTM4624	Single 4A Step-Down µModule Regulator	$4V \leq V_{IN} \leq 14V$, $0.6V \leq V_{OUT} \leq 5.5V$, 6.25mm × 6.25mm × 5.01mm BGA
LTM4625	Single 5A Step-Down µModule Regulator	$4V \leq V_{IN} \leq 20V$, $0.6V \leq V_{OUT} \leq 5.5V$, 6.25mm × 6.25mm × 5.01mm BGA
LTM4632	Ultrathin, Triple ±3A Step-Down µModule Regulator for DDR Memory	$3.6V \leq V_{IN} \leq 15V$, $0.6V \leq V_{OUT} \leq 2.5V$, 6.25mm × 6.25mm × 1.82mm LGA, 6.25mm × 6.25mm × 2.42mm BGA
LTM4643	Ultrathin, Quad 3A Step-Down µModule Regulator	$4V \leq V_{IN} \leq 20V$, $0.6V \leq V_{OUT} \leq 3.3V$, 9mm × 15mm × 1.82mm LGA, 9mm × 15mm × 2.42mm BGA
LTM4644	Quad 4A Step-Down µModule Regulator	$4V \leq V_{IN} \leq 14V$, $0.6V \leq V_{OUT} \leq 5.5V$, 9mm × 15mm × 5.01mm BGA